

# MATH 527 LECTURE 3: CONSERVATION LAWS II

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## Construction of weak solutions for simple initial data.

- Problem with method of characteristics:

1. Crossing; For example

$$u_t + u u_x = 0, \quad u(0, x) = \begin{cases} 1 & x < 0 \\ 0 & x > 0 \end{cases} \quad (1)$$

2. Void. For example

$$u_t + u u_x = 0, \quad u(0, x) = \begin{cases} 0 & x < 0 \\ 1 & x > 0 \end{cases} \quad (2)$$

- How does “weak solution” resolve these two issues?
  - Crossing.

Introduce a curve of “jump discontinuity”. This curve has to satisfy the jump condition:

$$\frac{dx}{dt} = s(x, t) = \frac{f(u_l) - f(u_r)}{u_l - u_r}. \quad (3)$$

- Note that we should only use “jump discontinuity” to resolve crossing. If we use it to deal with void, we would get unreasonable solutions.

**Example 1.** Consider

$$u_t + u u_x = 0, \quad u(0, x) = \begin{cases} 0 & x < 0 \\ 1 & x > 0 \end{cases} \quad (4)$$

We can define

$$u(t, x) = \begin{cases} 0 & x < t/2 \\ 1 & x > t/2 \end{cases}. \quad (5)$$

The jump condition is satisfied therefore  $u$  is indeed a weak solution.

However we claim that it is not reasonable. To see this, consider the following problem

$$u_t + u u_x = 0, \quad u(0, x) = \begin{cases} 0 & x < -\varepsilon \\ \frac{x + \varepsilon}{2\varepsilon} & -\varepsilon < x < \varepsilon \\ 1 & x > \varepsilon \end{cases} \quad (6)$$

We can clearly see that its solution approaches

$$u(t, x) = \begin{cases} 0 & x < 0 \\ x/t & 0 < x < t \\ 1 & x > t \end{cases}. \quad (7)$$

Therefore using discontinuities to fill “voids” should not be allowed.

- This leads to the idea of “entropy solution”. An entropy solution is a weak solution which further satisfies an “entropy condition” which excludes unreasonable solutions like the above. For 1D scalar equation, we can design the following
  - Toy entropy condition: For convex  $f(u)$ , a weak solution should only have discontinuities satisfying  $u_l > u_r$ .
  - This entropy condition is not useful in proofs due to the following reason. This condition is only meaningful when  $u$  is “piecewise  $C^1$ ”. However, in practice such information is usually very hard to establish and is often not true.

- A better one that is meaningful for any  $L^\infty$  function is the following:

$$\frac{u(x+a, t) - u(x, t)}{a} \leq \frac{E}{t} \quad (8)$$

for all  $a > 0, t > 0$ .

- Void.

Guided by the above example, we try to fill “voids” using simple wave solution as

$$u(t, x) = U\left(\frac{x - x_0}{t - t_0}\right). \quad (9)$$

Substituting into the equation

$$u_t + a(u) u_x = 0 \quad (10)$$

we obtain

$$a(U(\xi)) = \xi. \quad (11)$$

In particular, for Burgers equation we have

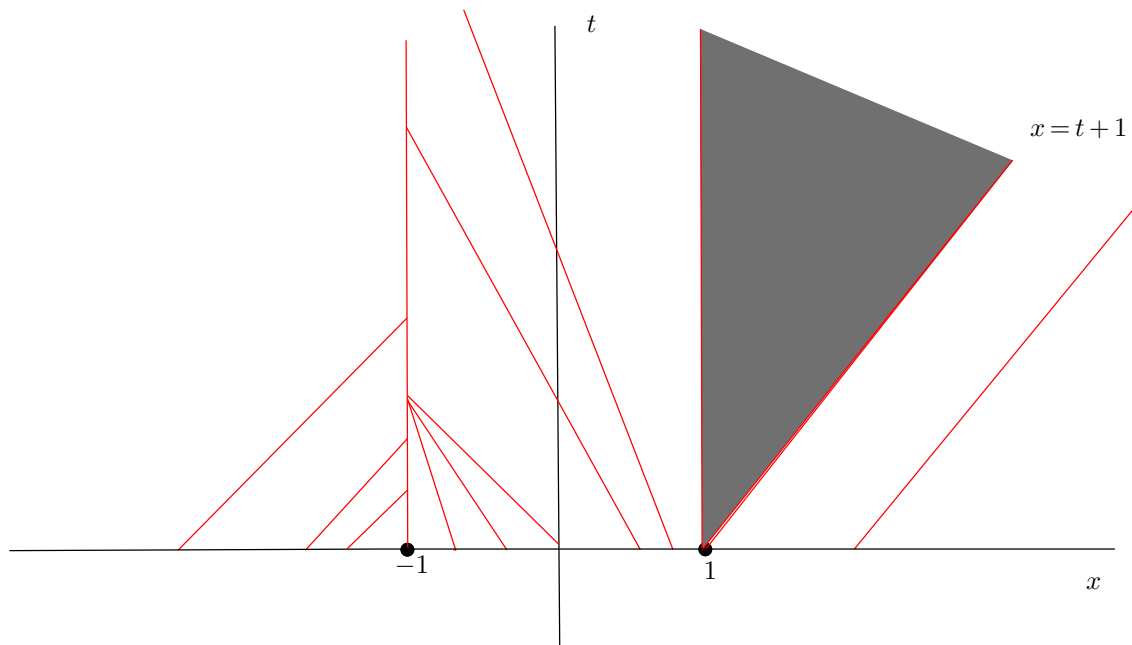
$$u(t, x) = U\left(\frac{x - x_0}{t - t_0}\right) = \frac{x - x_0}{t - t_0}. \quad (12)$$

Here  $(x_0, t_0)$  is the “tip” of the wedge-like void region.

**Example 2.** <sup>1</sup>Construct the entropy solution for (Sorry guys, how come I copied  $u = 0$  for  $|x| > 1$ ?)

$$u_t + \left(\frac{u^2}{2}\right)_x = 0, \quad u(0, x) = \begin{cases} 1 & |x| > 1 \\ -1 + |x| & |x| < 1 \end{cases}. \quad (13)$$

**Solution.** First we have to understand the structure of characteristics.



**Figure 1.** Structure of characteristics

1. Taken from J. Kevorkian, “Partial Differential Equations: Analytical Solution Techniques”.

From this picture it is clear that

1. Right of  $x = t + 1$ ,  $u = 1$ ;
2. Left of  $x = -1$ ,  $u = 1$ .
3. There is no characteristics in the gray area;
4. There are lots of crossings for  $x < 1$ . In particular, the very first crossing occurs at  $x = -1$  at  $t = 0$ .

Based on the above understanding, we try to construct the solution as follows:

1.  $u = 1$  for  $x > t + 1$ ;
2. A rarefaction wave  $\frac{x-1}{t}$  filling the gray area;
3. A shock emanating from the point  $x = -1, t = 0$ . To the right of the shock,  $u = 1$ . To the left, using the fact that  $u$  is constant along the straight lines, we see that  $u = \frac{x+1}{t-1}$  below  $x = -t$ , and  $u = \frac{x-1}{t+1}$  above it.

Now we determine the shock speed:

- Before meeting  $x = -t$ , we have

$$\frac{dx}{dt} = s = \frac{\left(\frac{x+1}{t-1}\right)^2 - 1}{\frac{x+1}{t-1} - 1} = \frac{\frac{x+1}{t-1} + 1}{2} = \frac{x+t}{2(t-1)}, \quad x(0) = -1 \quad (14)$$

This is a linear equation and can be solve to get

$$x = -2 + t + \sqrt{1-t} \quad (15)$$

- We compute the point of meeting (note that  $t$  needs to be positive):

$$-t = -2 + t + \sqrt{1-t} \implies t = 3/4. \quad (16)$$

So the shock is given by  $x = -2 + t + \sqrt{1-t}$  from  $x = -1, t = 0$  to  $x = -3/4, t = 3/4$ .

- The 2nd part of the shock is determined through solving

$$\frac{dx}{dt} = s = \frac{\frac{x-1}{t+1} + 1}{2} = \frac{x+t}{2(t+1)}, \quad x(3/4) = -3/4. \quad (17)$$

The solution is given by

$$x(t) = 2 + t - \sqrt{7(1+t)}. \quad (18)$$

- At this point it is clear that the shock will ultimately meet  $x = 1$ , and then “invading” into the gray area. To compute this 3rd part of the shock, we first get the “meeting point”:

$$1 = 2 + t - \sqrt{7(1+t)} \implies t = 6. \quad (19)$$

- The shock from the point  $x = 1, t = 6$  is governed by

$$\frac{dx}{dt} = \frac{\frac{x-1}{t} + 1}{2}, \quad x(6) = 1 \quad (20)$$

whose solution is

$$x(t) = 1 + t - \sqrt{6t}. \quad (21)$$

- As  $x(t) = 1 + t - \sqrt{6t} < 1 + t$  for all  $t$ , the shock will never meet  $x = 1 + t$ , the boundary of the right side.

**Remark 3.** Note that as  $t \rightarrow \infty$ , the solution approaches a constant  $u \equiv 1$ . In other words, all the “details” between  $-1 < x < 1$  are lost.