Math 348 Differential Geometry of Curves and Surfaces

Lecture 17: Gauss's Remarkable Theorem II

Xinwei Yu

Nov. 23, 2017

CAB 527, xinwei2@ualberta.ca Department of Mathematical & Statistical Sciences University of Alberta

Table of contents

- 1. Review
- 2. Remarks and Applications of the Gauss and Codazzi-Mainradi Equations
- 3. Surfaces of Constant Gaussian Curvature
- 4. Looking Back and Forward

Please do not hesitate to interrupt me if you have a question.

Review

The Equations and the theorem

Codazzi-Mainradi.

$$\mathbb{L}_{v} - \mathbb{M}_{u} = \mathbb{L}\Gamma_{12}^{1} + \mathbb{M}(\Gamma_{12}^{2} - \Gamma_{11}^{1}) - \mathbb{N}\Gamma_{11}^{2},
\mathbb{M}_{v} - \mathbb{N}_{u} = \mathbb{L}\Gamma_{22}^{1} + \mathbb{M}(\Gamma_{22}^{2} - \Gamma_{12}^{1}) - \mathbb{N}\Gamma_{12}^{2}.$$

Gauss.

$$\begin{split} \mathbb{E}K &= (\Gamma_{11}^2)_v - (\Gamma_{12}^2)_u + \Gamma_{11}^1 \Gamma_{12}^2 + \Gamma_{11}^2 \Gamma_{22}^2 - \Gamma_{12}^1 \Gamma_{11}^2 - (\Gamma_{12}^2)^2, \\ \mathbb{F}K &= (\Gamma_{12}^1)_u - (\Gamma_{11}^1)_v + \Gamma_{12}^2 \Gamma_{12}^1 - \Gamma_{11}^2 \Gamma_{22}^1 \\ &= (\Gamma_{12}^2)_v - (\Gamma_{22}^2)_u + \Gamma_{12}^1 \Gamma_{12}^2 - \Gamma_{22}^1 \Gamma_{11}^2 \\ \mathbb{G}K &= (\Gamma_{22}^1)_u - (\Gamma_{12}^1)_v + \Gamma_{22}^1 \Gamma_{11}^1 + \Gamma_{22}^2 \Gamma_{12}^1 - (\Gamma_{12}^1)^2 - \Gamma_{12}^2 \Gamma_{22}^1. \end{split}$$

Theorem

(Gauss's Theorema Egregium) The Gaussian curvature of a surface is preseved by local isometries.

Remarks and Applications of the

Equations

Gauss and Codazzi-Mainradi

Remarks on the Equations

- For every $\mathbb{E}, \mathbb{F}, \mathbb{G}, \mathbb{L}, \mathbb{M}, \mathbb{N}$ satisfy these equations, there is a unique surface patch with the two fundamental forms $\mathbb{E} du^2 + 2\mathbb{F} du dv + \mathbb{G} dv^2$ and $\mathbb{L} du^2 + 2\mathbb{M} du dv + \mathbb{N} dv^2$.
- Riemann curvature tensor.

$$R_{ijl}^{k} = \partial_{j} \Gamma_{il}^{k} - \partial_{l} \Gamma_{ij}^{k} + \Gamma_{jm}^{k} \Gamma_{il}^{m} - \Gamma_{lm}^{k} \Gamma_{ij}^{m}$$

where we have used the Einstein summation convention $a^mb_m=a^1b_1+a^2b_2$. Define $R_{ijkl}=g_{im}R^m_{jkl}$. Then $R_{1212}=-(\mathbb{LN}-\mathbb{M}^2)$.

Examples

Example

Is there a surface with first fundamental form $du^2 + \cos^2 u dv^2$ and $\cos^2 u du^2 + dv^2$?

- 1. Identify $\mathbb{E}, \mathbb{F}, \mathbb{G}, \mathbb{L}, \mathbb{M}, \mathbb{N}$;
- 2. Calculate K and Γ_{ij}^k ;
- 3. Check the Gauss and Codazzi-Mainradi equations.

Surfaces of Constant Gaussian Curvature

Motivation

Gauss's Theorem: Isometric then same K.

Natural question: Same K then isometric?

Answer:

- No.
 - Example: $(u, 4v, (u^2 + 4v^2)/2)$ and $(2u, 2v, u^2 + v^2)$;
 - Why are they not isometric?
- **Yes** if *K* is constant.

$$K=0$$

$K = 0 \Rightarrow$ isometric to plane.

- 1. $K = 0 \Rightarrow \text{ruled. } \sigma(u, v) = \gamma(u) + vI(u).$
- 2. Calculate $\mathbb{E}, \mathbb{F}, \mathbb{G}$.
- 3. $K = -\|\dot{I}\|^2 (1 (\dot{\gamma} \cdot I)^2) + (\dot{\gamma} \cdot \dot{I})^2$.
- 4. Two cases.
 - 4.1 $\dot{l} = 0$. cylinder or plane.
 - 4.2 $\dot{I} \neq 0$. $\dot{\gamma} \cdot (I \times \dot{I}) = 0$.

K = constant > 0

$$K = constant > 0 \Rightarrow isometric to a sphere.$$

- 1. Suffices to prove for K = 1.
- 2. Geodesic parametrization: $du^2 + \mathbb{G}dv^2$, $\mathbb{G}(0, v) = 1$, $\mathbb{G}_u(0, v) = 0$.
- 3. K = 1 becomes

$$-\frac{1}{2}\mathbb{G}_{uu}\mathbb{G}+\frac{1}{4}\mathbb{G}_u^2=\mathbb{G}^2.$$

- 4. Set $\mathbb{G} = g^2$, $g_{uu} + g = 0 \Rightarrow g(u, v) = A(v) \cos u + B(v) \sin u$.
- 5. $g(0, v) = 1, g_u(0, v) = 0 \Rightarrow A(v) = 1, B(v) = 0.$
- 6. First fundamental form $du^2 + \cos^2 u dv^2$.

$$K = constant < 0$$

$$K = constant < 0 \Rightarrow isometric to a pseudosphere.$$

Pseudosphere.

$$\sigma(u,v) = (f(u)\cos v, f(u)\sin v, g(u)), \ f(u) = ae^{u} + be^{-u}.$$

• **The proof.** See textbook p. 258.

Compact Surfaces

Theorem

Every connected compact¹ surface whose Gaussian curvature is constant is a sphere.

- Can we drop "connected"?
- Can we drop "compact"?
- "is a sphere" or "is isometry to a sphere"?

¹(in \mathbb{R}^d)=closed and bounded

Compact Surfaces: Proof

- Compact surface has at least one p with $K(p) > 0^2$.
- $\kappa_1 > \kappa_2$ somewhere leads to contradiction.
 - 1. $K = constant \Rightarrow \kappa_1$ reaches maximum at $p \Rightarrow \kappa_2$ reaches minimum at p;
 - 2. Around p make $\mathbb{F} = \mathbb{M} = 0$.
 - 3. Coddazi-Mainradi equations \Rightarrow

$$\mathbb{L}_{\nu} = \frac{1}{2} \mathbb{E}_{\nu} \left(\frac{\mathbb{L}}{\mathbb{E}} + \frac{\mathbb{N}}{\mathbb{G}} \right), \quad \mathbb{N}_{u} = \frac{1}{2} \mathbb{G}_{u} \left(\frac{\mathbb{L}}{\mathbb{E}} + \frac{\mathbb{N}}{\mathbb{G}} \right).$$

- 4. $\mathbb{E}_{v} = \mathbb{G}_{u} = 0$ at p;
- 5. $K(p) = -\frac{\mathbb{G}(\kappa_2)_{uu} \mathbb{E}(\kappa_1)_{vv}}{\mathbb{E}\mathbb{G}(\kappa_1 \kappa_2)} \leqslant 0.$
- 6. $\kappa_1 = \kappa_2$ **everywhere.** Together with K > 0 leads to sphere.

²Proposition 8.6.1 of textbook

Looking Back and Forward

Summary

Required: $\S 10.1,\ \S 10.2;$ Optional: $\S 10.3,\ \S 10.4$

- 1. Know how to use the equations to check existence of surfaces.
- 2. Know the isometry results for constant curvature surfaces.

See you next Tuesday!

The Gauss-Bonnet Theorem

- Generalization of $A + B + C = \pi$ for planar triangles.
- Related to the shape of the surface.