

A CONFORMING DG METHOD FOR THE BIHARMONIC EQUATION ON POLYTOPAL MESHES

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Abstract. A conforming discontinuous Galerkin finite element method is introduced for solving the biharmonic equation. This method, by its name, uses discontinuous approximations and keeps simple formulation of the conforming finite element method at the same time. The ultra simple formulation of the method will reduce programming complexity in practice. Optimal order error estimates in a discrete H^2 norm is established for the corresponding finite element solutions. Error estimates in the L^2 norm are also derived with a sub-optimal order of convergence for the lowest order element and an optimal order of convergence for all high order of elements. Numerical results are presented to confirm the theory of convergence.

Key words. finite element methods, weak Laplacian, biharmonic equations, polyhedral meshes.

1. Introduction

We consider the biharmonic equation of the form

$$\begin{aligned} (1) \quad & \Delta^2 u = f \quad \text{in } \Omega, \\ (2) \quad & u = 0 \quad \text{on } \partial\Omega, \\ (3) \quad & \frac{\partial u}{\partial n} = 0 \quad \text{on } \partial\Omega, \end{aligned}$$

where Ω is a bounded polytopal domain in \mathbb{R}^d .

The weak formulation of the boundary value problem (2) and (3) is seeking $u \in H_0^2(\Omega)$ satisfying

$$(4) \quad (\Delta u, \Delta v) = (f, v) \quad \forall v \in H_0^2(\Omega).$$

The H^2 conforming finite element method for the problem (1)-(3) keeps the same simple form as in (4): find $u_h \in V_h \subset H_0^2(\Omega)$ such that

$$(5) \quad (\Delta u_h, \Delta v) = (f, v) \quad \forall v \in V_h.$$

The early works in the area of finite elements (in 1960s) are mostly constructions of conforming and nonconforming elements for solving the biharmonic equation, for example, the Argyris element (1968), the Bell element (1969), the Bogner-Fox-Schmit rectangle (1965), the Hsieh-Clough-Tocher element (1965), the Fraeijs de Veubeke-Sander (1964) and the Morley element (1969), cf. [1, 2, 3, 11, 16, 44, 34]. Many more publications on C^1 -conforming and nonconforming finite elements can be found in [12, 14, 19, 22, 24, 25, 26, 27, 28, 29, 31, 33, 40, 41, 42, 47, 48, 56, 57, 58, 59, 60, 61, 62]. Some alternative methods are the interior penalty discontinuous Galerkin finite element methods [13, 17, 18, 35, 36, 46], the mixed finite elements of two Laplacians [4, 8, 9, 10, 15, 32, 43, 45], the Hellan-Herrmann-Johnson element [5, 20, 21, 30], and $H(\text{divdiv})$ mixed finite elements [6, 7, 23, 55].

An approach of avoiding construction of H^2 -conforming elements is to use discontinuous approximations. Due to the flexibility of discontinuous Galerkin (DG) finite element methods in element constructions and in mesh generations, many finite element methods have been developed using totally discontinuous polynomials. Here we are only interested in interior penalty discontinuous Galerkin (IPDG) methods since the proposed method shares the same finite element spaces with IPDG method [13, 17, 18, 35, 36, 46]. One obvious disadvantage of discontinuous finite element methods is their rather complicated formulations which are often necessary to guarantee well posedness and convergence of the methods. For example, the symmetric IPDG method for the biharmonic equation with homogenous boundary conditions [13, 17] has the following formulation:

$$\begin{aligned}
 (\Delta u_h, \Delta v)_{\mathcal{T}_h} &+ \sum_e \int_e (\{\nabla \Delta u_h\} \cdot [v] + \{\nabla \Delta v\} \cdot [u_h]) ds \\
 &+ \sum_e \int_e (\{\Delta u_h\} \cdot [\nabla v] + \{\Delta v\} \cdot [\nabla u_h]) ds \\
 (6) \quad &+ \sum_e \int_e (\sigma [u_h] \cdot [v] + \tau [\nabla u_h] [\nabla v]) ds = (f, v),
 \end{aligned}$$

where σ and τ are two parameters that need to be tuned.

The purpose of this work is to introduce a conforming DG finite element method for the biharmonic equation which has the following ultra simple formulation without any stabilizing/penalty terms and other mixed terms of lower dimension integrals in (6):

$$(7) \quad (\Delta_w u_h, \Delta_w v) = (f, v),$$

where Δ_w is called weak Laplacian, an approximation of Δ . The formulation (7) can be viewed as a counterpart of (5) for discontinuous approximations. The conforming DG method was first introduced in [52, 53] for second order elliptic equations. A conforming DG method, by name, means the method using the simple formulation of the conforming finite element method and the spaces of some DG finite element methods. That is, in the finite element equations, there is no penalty term neither any consistence-error control term.

This conforming DG finite element method (7) shares the same finite element space with the IPDG methods but having much simpler formulation. This simple formulation is obtained by defining weak Laplacian Δ_w appropriately. The idea here is to raise the degree of polynomials used to compute the weak Laplacian Δ_w . Using higher degree polynomials in computing the weak Laplacian will not change the size, neither the global sparsity of the stiffness matrix. Optimal order error estimates in a discrete H^2 for $k \geq 2$ and in L^2 norm for $k > 2$ are established for the corresponding finite element solutions. Numerical results are provided, confirming the theory.

The analysis of conforming DG finite element methods is based on that of the weak Galerkin finite element methods. [37] is the first weak Galerkin finite element work on the biharmonic equation. [39] is on the weak Galerkin method with the C^0 finite element spaces, for solving the biharmonic equation. A stabilizer free weak Galerkin method for the biharmonic equation is designed in [54]. This work is based on [54], by eliminating further the auxiliary variables of the function and the normal derivative on the inter-element edges or polygons.

2. A Conforming DG Finite Element Method

Let \mathcal{T}_h be a partition of the domain Ω consisting of polygons in two dimension or polyhedra in three dimension of size h , satisfying a set of conditions defined in [49] and additional conditions specified in [54]. For simplicity, in this work, we assume every polygon is convex, contains a circle of radius ch and has every edge of length ch , in 2D. In 3D, we assume every polyhedron is convex, contains a sphere of radius ch and has every face-polygon satisfying the 2D conditions above. Denote by \mathcal{E}_h the set of all edges or flat faces in \mathcal{T}_h , and let $\mathcal{E}_h^0 = \mathcal{E}_h \setminus \partial\Omega$ be the set of all interior edges or flat faces.

For simplicity, we adopt the following notations,

$$\begin{aligned} (v, w)_{\mathcal{T}_h} &= \sum_{T \in \mathcal{T}_h} (v, w)_T = \sum_{T \in \mathcal{T}_h} \int_T v w d\mathbf{x}, \\ \langle v, w \rangle_{\partial\mathcal{T}_h} &= \sum_{T \in \mathcal{T}_h} \langle v, w \rangle_{\partial T} = \sum_{T \in \mathcal{T}_h} \int_{\partial T} v w ds. \end{aligned}$$

Let $P_k(K)$ consist all the polynomials degree less or equal to k defined on K .

We define a finite element space V_h for $k \geq 2$ as follows

$$(8) \quad V_h = \{v \in L^2(\Omega) : v|_T \in P_k(T) \quad T \in \mathcal{T}_h\}.$$

Let T_1 and T_2 be two polygons/polyhedrons sharing e if $e \in \mathcal{E}_h^0$. Let v and \mathbf{q} be scalar and vector valued functions, the jumps $[v]$ and $[\mathbf{q}]$ are defined as

$$(9) \quad [v] = v|_{T_1} \mathbf{n}_1 + v|_{T_2} \mathbf{n}_2, \quad [\mathbf{q}] = \mathbf{q}|_{T_1} \cdot \mathbf{n}_1 + \mathbf{q}|_{T_2} \cdot \mathbf{n}_2,$$

and the averages $\{v\}$ and $\{\mathbf{q}\}$ are defined as

$$(10) \quad \{v\} = \frac{1}{2}(v|_{T_1} + v|_{T_2}) \quad \{\mathbf{q}\} = \frac{1}{2}(\mathbf{q}|_{T_1} + \mathbf{q}|_{T_2}).$$

If e is on $\partial\Omega$, then

$$(11) \quad \{v\} = 0, \quad \{\mathbf{q}\} = 0, \quad [v] = v\mathbf{n}, \quad [\mathbf{q}] = \mathbf{q} \cdot \mathbf{n}.$$

The new conforming DG finite element method for the biharmonic equation (1)-(3) is defined as follows.

Weak Galerkin Algorithm 1. *A numerical approximation for (1)-(3) can be obtained by seeking $u_h \in V_h$ satisfying the following equation:*

$$(12) \quad (\Delta_w u_h, \Delta_w v)_{\mathcal{T}_h} = (f, v) \quad \forall v \in V_h.$$

Next we will discuss how to compute the weak Laplacian $\Delta_w u_h$ and $\Delta_w v$ in (12). The concept of weak derivative was first introduced in [50, 49] for weak functions in weak Galerkin methods and was modified in [38, 51]. A weak Laplacian operator, denoted by

$$\Delta_w : V_h \rightarrow \{q \in L^2(\Omega) : q|_T \in P_j(T)\}$$

for some $j > k$ to be specified late, is defined as the unique solution of the following equation

$$(13) \quad (\Delta_w v, \varphi)_T = (v, \Delta\varphi)_T - \langle \{v\}, \nabla\varphi \cdot \mathbf{n} \rangle_{\partial T} + \langle \{\nabla v\} \cdot \mathbf{n}, \varphi \rangle_{\partial T} \quad \forall \varphi \in P_j(T).$$

We remark again that $\{v\}$ and $\{\nabla v\}$ are the averages on two neighboring elements. Thus $\Delta_w v$ is defined locally but supported globally on a patch of elements.

Lemma 2.1. *Let $\phi \in H^2(\Omega)$, then on any $T \in \mathcal{T}_h$,*

$$(14) \quad \Delta_w \phi = \mathbb{Q}_h(\Delta \phi),$$

where \mathbb{Q}_h is a locally defined L^2 projections onto $P_j(T)$ on each element $T \in \mathcal{T}_h$.

Proof. It is not hard to see that for any $\tau \in P_j(T)$ we have

$$\begin{aligned} (\Delta_w \phi, \tau)_T &= (\phi, \Delta \tau)_T + \langle \{\nabla \phi\} \cdot \mathbf{n}, \tau \rangle_{\partial T} - \langle \{\phi\}, \nabla \tau \cdot \mathbf{n} \rangle_{\partial T} \\ &= (\phi, \Delta \tau)_T + \langle \nabla \phi \cdot \mathbf{n}, \tau \rangle_{\partial T} - \langle \phi, \nabla \tau \cdot \mathbf{n} \rangle_{\partial T} \\ &= (\Delta \phi, \tau)_T = (\mathbb{Q}_h \Delta \phi, \tau)_T, \end{aligned}$$

which implies (14). We complete the proof. □

3. Well Posedness

First we define a semi-norm $\|\cdot\|$ as

$$(15) \quad \|v\|^2 = (\Delta_w v, \Delta_w v)_{\mathcal{T}_h}.$$

Then we introduce a discrete H^2 norm as follows:

$$(16) \quad \|v\|_{2,h} = \left(\sum_{T \in \mathcal{T}_h} (\|\Delta v\|_T^2 + h_T^{-3} \|v\|_{\partial T}^2 + h_T^{-1} \|\nabla v\|_{\partial T}^2) \right)^{\frac{1}{2}}.$$

The following lemma indicates that the two norms $\|\cdot\|_{2,h}$ and $\|\cdot\|$ are equivalent.

First we need the following trace inequality. For any function $\varphi \in H^1(T)$, the trace inequality holds true (see [49] for details):

$$(17) \quad \|\varphi\|_e^2 \leq C (h_T^{-1} \|\varphi\|_T^2 + h_T \|\nabla \varphi\|_T^2).$$

Lemma 3.1. *There exist two positive constants C_1 and C_2 such that for any $v \in V_h$, we have*

$$(18) \quad C_1 \|v\|_{2,h} \leq \|v\| \leq C_2 \|v\|_{2,h},$$

where the two norms are defined in (15) and (16).

Proof. For any $v \in V_h$, it follows from the definition of weak Laplacian (13) and integration by parts that

$$\begin{aligned} (\Delta_w v, \varphi)_T &= (v, \Delta \varphi)_T - \langle \{v\}, \nabla \varphi \cdot \mathbf{n} \rangle_{\partial T} + \langle \{\nabla v\} \cdot \mathbf{n}, \varphi \rangle_{\partial T} \\ &= -(\nabla v, \nabla \varphi)_T + \langle v - \{v\}, \nabla \varphi \cdot \mathbf{n} \rangle_{\partial T} + \langle \{\nabla v\} \cdot \mathbf{n}, \varphi \rangle_{\partial T} \\ (19) \quad &= (\Delta v, \varphi)_T + \langle v - \{v\}, \nabla \varphi \cdot \mathbf{n} \rangle_{\partial T} + \langle (\{\nabla v\} - \nabla v) \cdot \mathbf{n}, \varphi \rangle_{\partial T}. \end{aligned}$$

By letting $\varphi = \Delta_w v$ in (19) we arrive at

$$\|\Delta_w v\|_T^2 = (\Delta v, \Delta_w v)_T + \langle v - \{v\}, \nabla(\Delta_w v) \cdot \mathbf{n} \rangle_{\partial T} + \langle (\{\nabla v\} - \nabla v) \cdot \mathbf{n}, \Delta_w v \rangle_{\partial T}$$

It is easy to see that the following equations hold true for v on T with $e \subset \partial T$,

$$(20) \quad \|v - \{v\}\|_e = \|[v]\|_e \quad \text{if } e \subset \partial \Omega, \quad \|v - \{v\}\|_e = \frac{1}{2} \|[v]\|_e \quad \text{if } e \in \mathcal{E}_h^0.$$

and

$$(21) \quad \begin{aligned} \|(\nabla v - \{\nabla v\}) \cdot \mathbf{n}\|_e &= \|\nabla v\|_e \quad \text{if } e \subset \partial \Omega, \\ \|(\nabla v - \{\nabla v\}) \cdot \mathbf{n}\|_e &= \frac{1}{2} \|\nabla v\|_e \quad \text{if } e \in \mathcal{E}_h^0. \end{aligned}$$

From the trace inequality (17), (20)-(21) and the inverse inequality we have

$$\begin{aligned} \|\Delta_w v\|_T^2 &\leq \|\Delta v\|_T \|\Delta_w v\|_T + \|v - \{v\}\|_{\partial T} \|\nabla(\Delta_w v)\|_{\partial T} \\ &\quad + \|(\{\nabla v\} - \nabla v) \cdot \mathbf{n}\|_{\partial T} \|\Delta_w v\|_{\partial T} \\ &\leq C(\|\Delta v\|_T + h_T^{-3/2} \|v\|_{\partial T} + h_T^{-1/2} \|[\nabla v]\|_{\partial T}) \|\Delta_w v\|_T, \end{aligned}$$

which implies

$$\|\Delta_w v\|_T \leq C \left(\|\Delta v\|_T + h_T^{-3/2} \|v\|_{\partial T} + h_T^{-1/2} \|[\nabla v]\|_{\partial T} \right),$$

and consequently

$$\|v\| \leq C_2 \|v\|_{2,h}.$$

Next we will prove

$$\sum h_T^{-3} \|v\|_{\partial T}^2 \leq C \|v\|.$$

It follows from (19) that for any $\varphi \in P_j(T)$,

$$\begin{aligned} (\Delta_w v, \varphi)_T &= (\Delta v, \varphi)_T + \langle v - \{v\}, \nabla \varphi \cdot \mathbf{n} \rangle_{\partial T} \\ &\quad + \langle (\{\nabla v\} - \nabla v) \cdot \mathbf{n}, \varphi \rangle_{\partial T}. \end{aligned} \tag{22}$$

By Lemma 3.1 in [54], there exist a φ_0 such that for $e \subset \partial T$,

$$\begin{aligned} (\Delta v, \varphi_0)_T &= 0, \\ (\{\nabla v\} - \nabla v) \cdot \mathbf{n}, \varphi_0 \rangle_{\partial T} &= 0, \\ \langle v - \{v\}, \nabla \varphi_0 \cdot \mathbf{n} \rangle_{\partial T \setminus e} &= 0, \\ \langle v - \{v\}, \nabla \varphi_0 \cdot \mathbf{n} \rangle_{\partial T} &= \|v - \{v\}\|_e^2, \\ \|\varphi_0\|_T &\leq Ch_T^{3/2} \|v - \{v\}\|_e. \end{aligned} \tag{23}$$

Letting $\varphi = \varphi_0$ in (22) yields

$$\|v - \{v\}\|_e^2 = (\Delta_w v, \varphi_0)_T \leq \|\Delta_w v\|_T \|\varphi_0\|_T \leq Ch_T^{3/2} \|\Delta_w v\|_T \|v - \{v\}\|_e,$$

where φ_0 is defined in (23). It implies

$$\|v - \{v\}\|_e \leq Ch_T^{3/2} \|\Delta_w v\|_T.$$

Taking the summation of the above equation over $T \in \mathcal{T}_h$ and using (20), one has

$$\sum_{T \in \mathcal{T}_h} h_T^{-3} \|v\|_{\partial T}^2 \leq C \|v\|^2. \tag{24}$$

Similarly, by Lemma 3.2 in [54], we can have

$$\sum_{T \in \mathcal{T}_h} h_T^{-1} \|[\nabla v]\|_{\partial T}^2 \leq C \|v\|^2. \tag{25}$$

Finally, by letting $\varphi = \Delta v$ in (22) we arrive at

$$\begin{aligned} \|\Delta v\|_T^2 &= (\Delta v, \Delta_w v)_T - \langle v - \{v\}, \nabla(\Delta_w v) \cdot \mathbf{n} \rangle_{\partial T} \\ &\quad - \langle (\{\nabla v\} - \nabla v) \cdot \mathbf{n}, \Delta_w v \rangle_{\partial T}. \end{aligned}$$

Using the trace inequality (17), the inverse inequality and (24)-(25), one has

$$\|\Delta v\|_T^2 \leq C \|\Delta_w v\|_T \|\Delta v\|_T,$$

which gives

$$\sum_{T \in \mathcal{T}_h} \|\Delta v\|_T^2 \leq C \|v\|^2.$$

We complete the proof. □

Lemma 3.2. *The finite element scheme (12) has a unique solution.*

Proof. It suffices to show that the solution of (12) is trivial if $f = g = \phi = 0$. It follows that

$$(\Delta_w u_h, \Delta_w u_h)_{\mathcal{T}_h} = 0.$$

Then the norm equivalence (18) implies $\|u_h\|_{2,h} = 0$, i.e.

$$\sum_{T \in \mathcal{T}_h} \|\Delta u_h\|_T^2 = 0, \quad \sum_{T \in \mathcal{T}_h} h_T^{-3} \| [u_h] \| = 0, \quad \sum_{T \in \mathcal{T}_h} h_T^{-1} \| [\nabla u_h] \| = 0.$$

Therefore, u_h is a smooth harmonic function on Ω and $u_h = 0$ on $\partial\Omega$. Thus we have $u_h = 0$, which completes the proof. \square

4. An Error Equation

Let $e_h = u - u_h$. Next we derive an error equation that e_h satisfies.

Lemma 4.1. *For any $v \in V_h$, we have*

$$(26) \quad (\Delta_w e_h, \Delta_w v)_{\mathcal{T}_h} = \ell_1(u, v) + \ell_2(u, v),$$

where

$$\begin{aligned} \ell_1(u, v) &= \langle \nabla(\mathbb{Q}_h \Delta u - \Delta u) \cdot \mathbf{n}, v - \{v\} \rangle_{\partial T_h}, \\ \ell_2(u, v) &= \langle \Delta u - \mathbb{Q}_h \Delta u, (\nabla v - \{\nabla v\}) \cdot \mathbf{n} \rangle_{\partial T}. \end{aligned}$$

Proof. Testing (1) by $v \in V_h$ and using the fact that $\sum_{T \in \mathcal{T}_h} \langle \nabla(\Delta u) \cdot \mathbf{n}, \{v\} \rangle_{\partial T} = 0$ and $\sum_{T \in \mathcal{T}_h} \langle \Delta u, \{\nabla v\} \cdot \mathbf{n} \rangle_{\partial T} = 0$ and integration by parts, we arrive at

$$\begin{aligned} (f, v) &= (\Delta^2 u, v)_{\mathcal{T}_h} \\ (27) \quad &= (\Delta u, \Delta v)_{\mathcal{T}_h} - \langle \Delta u, \nabla v \cdot \mathbf{n} \rangle_{\partial T_h} + \langle \nabla(\Delta u) \cdot \mathbf{n}, v \rangle_{\partial T_h} \\ &= (\Delta u, \Delta v)_{\mathcal{T}_h} - \langle \Delta u, (\nabla v - \{\nabla v\}) \cdot \mathbf{n} \rangle_{\partial T_h} \\ &\quad + \langle \nabla(\Delta u) \cdot \mathbf{n}, v - \{v\} \rangle_{\partial T_h}. \end{aligned}$$

Next we investigate the term $(\Delta u, \Delta v)_{\mathcal{T}_h}$ in the above equation. Using (14), integration by parts and the definition of weak Laplacian (13), we have

$$\begin{aligned} (\Delta u, \Delta v)_{\mathcal{T}_h} &= (\mathbb{Q}_h \Delta u, \Delta v)_{\mathcal{T}_h} \\ &= (v, \Delta(\mathbb{Q}_h \Delta u))_T + \langle \nabla v \cdot \mathbf{n}, \mathbb{Q}_h \Delta u \rangle_{\partial T} - \langle v, \nabla(\mathbb{Q}_h \Delta u) \cdot \mathbf{n} \rangle_{\partial T} \\ &= (\Delta_w v, \mathbb{Q}_h \Delta u)_T - \langle v - \{v\}, \nabla(\mathbb{Q}_h \Delta u) \cdot \mathbf{n} \rangle_{\partial T} + \langle (\nabla v - \{\nabla v\}) \cdot \mathbf{n}, \mathbb{Q}_h \Delta u \rangle_{\partial T} \\ &= (\Delta_w u, \Delta_w v)_T - \langle v - \{v\}, \nabla(\mathbb{Q}_h \Delta u) \cdot \mathbf{n} \rangle_{\partial T} + \langle (\nabla v - \{\nabla v\}) \cdot \mathbf{n}, \mathbb{Q}_h \Delta u \rangle_{\partial T}. \end{aligned}$$

Combining the above two equations gives

$$\begin{aligned} (f, v) &= (\Delta^2 u, v)_{\mathcal{T}_h} \\ &= (\Delta_w u, \Delta_w v)_{\mathcal{T}_h} - \langle v - \{v\}, \nabla(\mathbb{Q}_h \Delta u - \Delta u) \cdot \mathbf{n} \rangle_{\partial T_h} \\ (28) \quad &\quad - \langle (\nabla v - \{\nabla v\}) \cdot \mathbf{n}, \Delta u - \mathbb{Q}_h \Delta u \rangle_{\partial T}, \end{aligned}$$

which implies that

$$(\Delta_w u, \Delta_w v)_{\mathcal{T}_h} = (f, v) + \ell_1(u, v) + \ell_2(u, v).$$

The error equation follows from subtracting (12) from the above equation,

$$(\Delta_w e_h, \Delta_w v)_{\mathcal{T}_h} = \ell_1(u, v) + \ell_2(u, v).$$

We have proved the lemma. \square

5. An Error Estimate in H^2

We start this section by defining some approximation operator. Let Q_h be the element-wise defined L^2 projection onto $P_k(T)$ on each element T .

Lemma 5.1. *Let $k \geq 2$ and $w \in H^{\max\{k+1,4\}}(\Omega)$. There exists a constant C such that the following estimates hold true:*

$$(29) \quad \left(\sum_{T \in \mathcal{T}_h} h_T \|\Delta w - Q_h \Delta w\|_{\partial T}^2\right)^{\frac{1}{2}} \leq Ch^{k-1} \|w\|_{k+1},$$

$$(30) \quad \left(\sum_{T \in \mathcal{T}_h} h_T^3 \|\nabla(\Delta w - Q_h \Delta w)\|_{\partial T}^2\right)^{\frac{1}{2}} \leq Ch^{k-1} (\|w\|_{k+1} + h\delta_{k,2} \|w\|_4).$$

Here $\delta_{i,j}$ is the usual Kronecker's delta with value 1 when $i = j$ and value 0 otherwise.

The above lemma can be proved by using the trace inequality (17) and the definition of Q_h . The proof can also be found in [37].

Lemma 5.2. *Let $w \in H^{\max\{k+1,4\}}(\Omega)$, and $v \in V_h$. There exists a constant C such that*

$$(31) \quad |\ell_1(w, v)| \leq Ch^{k-1} (\|w\|_{k+1} + h\delta_{k,2} \|w\|_4) \|v\|.$$

$$(32) \quad |\ell_2(w, v)| \leq Ch^{k-1} |w|_{k+1} \|v\|.$$

Proof. Using the Cauchy-Schwartz inequality, (29), (30), (20), (21) and (18), we have

$$\begin{aligned} \ell_1(w, v) &= \left| \sum_{T \in \mathcal{T}_h} \langle \nabla(\Delta w - Q_h \Delta w) \cdot \mathbf{n}, v - \{v\} \rangle_{\partial T} \right| \\ &\leq \left(\sum_{T \in \mathcal{T}_h} h_T^3 \|\nabla(\Delta w - Q_h \Delta w)\|_{\partial T}^2 \right)^{\frac{1}{2}} \left(\sum_{T \in \mathcal{T}_h} h_T^{-3} \|v - \{v\}\|_{\partial T}^2 \right)^{\frac{1}{2}} \\ &\leq \left(\sum_{T \in \mathcal{T}_h} h_T^3 \|\nabla(\Delta w - Q_h \Delta w)\|_{\partial T}^2 \right)^{\frac{1}{2}} \left(\sum_{T \in \mathcal{T}_h} h_T^{-3} \|[v]\|_{\partial T}^2 \right)^{\frac{1}{2}} \\ (33) \quad &\leq Ch^{k-1} (\|w\|_{k+1} + h\delta_{k,2} \|w\|_4) \|v\|, \end{aligned}$$

and

$$\begin{aligned} \ell_2(w, v) &= \left| \sum_{T \in \mathcal{T}_h} \langle \Delta w - Q_h \Delta w, (\nabla v - \{\nabla v\}) \cdot \mathbf{n} \rangle_{\partial T} \right| \\ &\leq \left(\sum_{T \in \mathcal{T}_h} h_T \|\Delta w - Q_h \Delta w\|_{\partial T}^2 \right)^{\frac{1}{2}} \left(\sum_{T \in \mathcal{T}_h} h_T^{-1} \|[\nabla v]\|_{\partial T}^2 \right)^{\frac{1}{2}} \\ (34) \quad &\leq Ch^{k-1} \|w\|_{k+1} \|v\|. \end{aligned}$$

We complete the proof. □

Lemma 5.3. *Let $w \in H^{\max\{k+1,4\}}(\Omega)$, then*

$$(35) \quad \|w - Q_h w\| \leq Ch^{k-1} |w|_{k+1}.$$

Proof. For any $T \in \mathcal{T}_h$, it follows from (13), integration by parts, (17) and inverse inequality that for $w \in P_j(T)$,

$$\begin{aligned}
\|\Delta_w(w - Q_h w)\|_T^2 &= (\Delta_w(w - Q_h w), \Delta_w(w - Q_h w))_T \\
&= (w - Q_h w, \Delta(\Delta_w(w - Q_h w)))_T \\
&\quad - \langle \{w - Q_h w\}, \nabla(\Delta_w(w - Q_h w)) \cdot \mathbf{n} \rangle_{\partial T} \\
&\quad + \langle \{\nabla w - \nabla Q_h w\} \cdot \mathbf{n}, \Delta_w(w - Q_h w) \rangle_{\partial T} \\
&\leq C(h_T^{-2} \|w - Q_h w\|_T + h_T^{-3/2} \|w - Q_h w\|_{\partial T} \\
&\quad + h_T^{-1/2} \|\nabla w - \nabla Q_h w\|_{\partial T}) \|\Delta_w(w - Q_h w)\|_T \\
&\leq Ch^{k-1} |w|_{k+1, T} \|\Delta_w(w - Q_h w)\|_T,
\end{aligned}$$

which implies

$$\|\Delta_w(w - Q_h w)\|_T \leq Ch^{k-1} |w|_{k+1, T}.$$

Taking the summation over $T \in \mathcal{T}_h$, we have proved the lemma. \square

Theorem 5.1. *Let $u_h \in V_h$ be the finite element solution arising from (12). Assume that the exact solution $u \in H^{\max\{k+1, 4\}}(\Omega)$. Then, there exists a constant C such that*

$$(36) \quad \|u - u_h\| \leq Ch^{k-1} (\|u\|_{k+1} + h\delta_{k,2} \|u\|_4).$$

Proof. Let $\epsilon_h = Q_h u - u_h$. Then it is straightforward to obtain

$$\begin{aligned}
(37) \quad \|e_h\|^2 &= (\Delta_w e_h, \Delta_w e_h)_{\mathcal{T}_h} \\
&= (\Delta_w e_h, \Delta_w(u - u_h))_{\mathcal{T}_h} \\
&= (\Delta_w e_h, \Delta_w(Q_h u - u_h))_{\mathcal{T}_h} + (\Delta_w e_h, \Delta_w(u - Q_h u))_{\mathcal{T}_h} \\
&= (\Delta_w e_h, \Delta_w \epsilon_h)_{\mathcal{T}_h} + (\Delta_w e_h, \Delta_w(u - Q_h u))_{\mathcal{T}_h}.
\end{aligned}$$

We will bound the term $(\Delta_w e_h, \Delta_w \epsilon_h)_{\mathcal{T}_h}$ on right hand side of (37) first. Letting $v = \epsilon_h \in V_h$ in (26) and using (31)-(32) and (35), we have

$$\begin{aligned}
(38) \quad |(\Delta_w e_h, \Delta_w \epsilon_h)_{\mathcal{T}_h}| &\leq |\ell_1(u, \epsilon_h)| + |\ell_2(u, \epsilon_h)| \\
&\leq Ch^{k-1} (\|u\|_{k+1} + h\delta_{k,2} \|u\|_4) \|e_h\| \\
&\leq Ch^{k-1} (\|u\|_{k+1} + h\delta_{k,2} \|u\|_4) (\|u - Q_h u\| + \|u - u_h\|) \\
&\leq Ch^{2(k-1)} (\|u\|_{k+1}^2 + h^2 \delta_{k,2} \|u\|_4^2) + \frac{1}{4} \|e_h\|^2.
\end{aligned}$$

To bound the second term on right hand side of (37), we have by (35),

$$\begin{aligned}
(39) \quad |(\Delta_w e_h, \Delta_w(u - Q_h u))_{\mathcal{T}_h}| &\leq C \|u - Q_h u\| \|e_h\| \\
&\leq Ch^{2(k-1)} \|u\|_{k+1}^2 + \frac{1}{4} \|e_h\|^2.
\end{aligned}$$

Combining the estimates (38) and (39) with (37), we arrive

$$\|e_h\| \leq Ch^{k-1} (\|u\|_{k+1} + h\delta_{k,2} \|u\|_4),$$

which completes the proof. \square

6. Error Estimates in L^2 Norm

In this section, we will obtain an error bound for the finite element solution u_h in L^2 norm.

The dual problem considered has the following form,

$$(40) \quad \Delta^2 w = e_h \quad \text{in } \Omega,$$

$$(41) \quad w = 0 \quad \text{on } \partial\Omega,$$

$$(42) \quad \nabla w \cdot \mathbf{n} = 0 \quad \text{on } \partial\Omega.$$

Assume that the H^4 regularity holds,

$$(43) \quad \|w\|_4 \leq C\|e_h\|.$$

Theorem 6.1. *Let $u_h \in V_h$ be the finite element solution arising from (12). Assume that the exact solution $u \in H^{k+1}(\Omega)$ and (43) holds true. Then, there exists a constant C such that*

$$(44) \quad \|u - u_h\| \leq Ch^{k+1-\delta_{k,2}} (\|u\|_{k+1} + h\delta_{k,2}\|u\|_4).$$

Proof. Testing (40) by e_h and using the fact that $\sum_{T \in \mathcal{T}_h} \langle \nabla(\Delta w) \cdot \mathbf{n}, \{e_h\} \rangle_{\partial T} = 0$ and $\sum_{T \in \mathcal{T}_h} \langle \Delta w, \{\nabla e_h\} \cdot \mathbf{n} \rangle_{\partial T} = 0$ and integration by parts, we arrive at

$$\begin{aligned} \|e_h\|^2 &= (\Delta^2 w, e_h)_{\mathcal{T}_h} \\ &= (\Delta w, \Delta e_h)_{\mathcal{T}_h} - \langle \Delta w, \nabla e_h \cdot \mathbf{n} \rangle_{\partial \mathcal{T}_h} + \langle \nabla(\Delta w) \cdot \mathbf{n}, e_h \rangle_{\partial \mathcal{T}_h} \\ &= (\Delta w, \Delta e_h)_{\mathcal{T}_h} - \langle \Delta w, (\nabla e_h - \{\nabla e_h\}) \cdot \mathbf{n} \rangle_{\partial \mathcal{T}_h} \\ &\quad + \langle \nabla(\Delta w) \cdot \mathbf{n}, e_h - \{e_h\} \rangle_{\partial \mathcal{T}_h} \\ &= (\mathbb{Q}_h \Delta w, \Delta e_h)_{\mathcal{T}_h} + (\Delta w - \mathbb{Q}_h \Delta w, \Delta e_h)_{\mathcal{T}_h} \\ &\quad - \langle \Delta w, (\nabla e_h - \{\nabla e_h\}) \cdot \mathbf{n} \rangle_{\partial \mathcal{T}_h} + \langle \nabla(\Delta w) \cdot \mathbf{n}, e_h - \{e_h\} \rangle_{\partial \mathcal{T}_h}. \end{aligned}$$

It follows from integration by parts, the definition of weak Laplacian (13) and (14),

$$\begin{aligned} &(\mathbb{Q}_h \Delta w, \Delta e_h)_{\mathcal{T}_h} \\ &= (e_h, \Delta(\mathbb{Q}_h \Delta w))_T + \langle \nabla e_h \cdot \mathbf{n}, \mathbb{Q}_h \Delta w \rangle_{\partial T} - \langle e_h, \nabla(\mathbb{Q}_h \Delta w) \cdot \mathbf{n} \rangle_{\partial T} \\ &= (\Delta_w e_h, \mathbb{Q}_h \Delta w)_T - \langle e_h - \{e_h\}, \nabla(\mathbb{Q}_h \Delta w) \cdot \mathbf{n} \rangle_{\partial T} \\ &\quad + \langle (\nabla e_h - \{\nabla e_h\}) \cdot \mathbf{n}, \mathbb{Q}_h \Delta w \rangle_{\partial T} \\ &= (\Delta_w w, \Delta_w e_h)_T - \langle e_h - \{e_h\}, \nabla(\mathbb{Q}_h \Delta w) \cdot \mathbf{n} \rangle_{\partial T} \\ &\quad + \langle (\nabla e_h - \{\nabla e_h\}) \cdot \mathbf{n}, \mathbb{Q}_h \Delta w \rangle_{\partial T}. \end{aligned}$$

Combining the two equations above implies

$$\begin{aligned} \|e_h\|^2 &= (\Delta_w w, \Delta_w e_h)_{\mathcal{T}_h} + (\Delta w - \mathbb{Q}_h \Delta w, \Delta e_h)_{\mathcal{T}_h} \\ &\quad + \ell_1(w, e_h) + \ell_2(w, e_h). \end{aligned}$$

By simple manipulation and (26), we have

$$\begin{aligned} (\Delta_w w, \Delta_w e_h)_{\mathcal{T}_h} &= (\Delta_w \mathbb{Q}_h w, \Delta_w e_h)_{\mathcal{T}_h} + (\Delta_w(w - \mathbb{Q}_h w), \Delta_w e_h)_{\mathcal{T}_h} \\ &= \ell_1(u, \mathbb{Q}_h w) + \ell_2(u, \mathbb{Q}_h w) + (\Delta_w(w - \mathbb{Q}_h w), \Delta_w e_h)_{\mathcal{T}_h}. \end{aligned}$$

Combining the two equations above implies

$$\begin{aligned} \|e_h\|^2 &= \ell_1(u, \mathbb{Q}_h w) + \ell_2(u, \mathbb{Q}_h w) + (\Delta_w e_h, \Delta_w(w - \mathbb{Q}_h w))_{\mathcal{T}_h} \\ &\quad + (\Delta w - \mathbb{Q}_h \Delta w, \Delta e_h)_{\mathcal{T}_h} + \ell_1(w, e_h) + \ell_2(w, e_h) \\ &= I_1 + I_2 + I_3 + I_4 + I_5 + I_6. \end{aligned}$$

Next, we will estimate all the terms on the right hand side of the above equation. Using the Cauchy-Schwartz inequality, (29)-(30), (20) and (33), we have

$$\begin{aligned}
I_1 &= \ell_1(u, Q_h w) = \left| \sum_{T \in \mathcal{T}_h} \langle \nabla(\Delta u - \mathbb{Q}_h \Delta u) \cdot \mathbf{n}, Q_h w - \{Q_h w\} \rangle_{\partial T} \right| \\
&\leq \left(\sum_{T \in \mathcal{T}_h} h_T^3 \|\nabla(\Delta u - \mathbb{Q}_h \Delta u)\|_{\partial T}^2 \right)^{\frac{1}{2}} \left(\sum_{T \in \mathcal{T}_h} h_T^{-3} \|[Q_h w]\|_{\partial T}^2 \right)^{\frac{1}{2}} \\
&\leq \left(\sum_{T \in \mathcal{T}_h} h_T^3 \|\nabla(\Delta u - \mathbb{Q}_h \Delta u)\|_{\partial T}^2 \right)^{\frac{1}{2}} \left(\sum_{T \in \mathcal{T}_h} h_T^{-3} \|[Q_h w - w]\|_{\partial T}^2 \right)^{\frac{1}{2}} \\
&\leq Ch^{k+1-\delta_{k,2}} (\|u\|_{k+1} + h\delta_{k,2}\|u\|_4) \|w\|_4,
\end{aligned}$$

Similarly, by the Cauchy-Schwartz inequality, (29)-(30), (21) and (34), we have

$$\begin{aligned}
I_2 &= \ell_2(u, Q_h w) = \left| \sum_{T \in \mathcal{T}_h} \langle \Delta u - \mathbb{Q}_h \Delta u, (\nabla Q_h w - \{\nabla Q_h w\}) \cdot \mathbf{n} \rangle_{\partial T} \right| \\
&\leq \left(\sum_{T \in \mathcal{T}_h} h_T^{-1} \|\Delta u - \mathbb{Q}_h \Delta u\|_{\partial T}^2 \right)^{\frac{1}{2}} \left(\sum_{T \in \mathcal{T}_h} h_T \|\nabla Q_h w - \nabla w\|_{\partial T}^2 \right)^{\frac{1}{2}} \\
&\leq Ch^{k+1-\delta_{k,2}} \|u\|_{k+2} \|w\|_4.
\end{aligned}$$

The estimates (36) and (35) give

$$I_3 \leq Ch^{k+1} \|u\|_{k+1} \|w\|_4.$$

To estimate I_4 , we need to bound $\|\Delta e_h\|_T$. By (18), (35), (36) and the definition of Q_h , we have

$$\begin{aligned}
\sum_{T \in \mathcal{T}_h} \|\Delta e_h\|_T^2 &\leq \sum_{T \in \mathcal{T}_h} \|\Delta \epsilon_h\|_T^2 + \sum_{T \in \mathcal{T}_h} \|\Delta(u - Q_h u)\|_T^2 \\
&\leq C(h^{k-1} \|u\|_{k+1} + \|\epsilon_h\|^2) \\
&\leq C(h^{k-1} \|u\|_{k+1} + \|e_h\|^2 + \|Q_h u - u\|^2) \\
&\leq Ch^{k-1} \|u\|_{k+1}.
\end{aligned}$$

The above estimate and the definition of \mathbb{Q}_h imply

$$I_4 \leq Ch^{k+1} \|u\|_{k+1} \|w\|_4.$$

Using the Cauchy-Schwartz inequality, (20), (29), (18), (35) and (36), we have

$$\begin{aligned}
 I_5 &= \ell_1(w, e_h) = \left| \sum_{T \in \mathcal{T}_h} \langle \nabla(\Delta w - \mathbb{Q}_h \Delta w) \cdot \mathbf{n}, e_h - \{e_h\} \rangle_{\partial T} \right| \\
 &\leq \left(\sum_{T \in \mathcal{T}_h} h_T^3 \|\nabla(\Delta w - \mathbb{Q}_h \Delta w)\|_{\partial T}^2 \right)^{\frac{1}{2}} \left(\sum_{T \in \mathcal{T}_h} h_T^{-3} \|e_h - \{e_h\}\|_{\partial T}^2 \right)^{\frac{1}{2}} \\
 &\leq \left(\sum_{T \in \mathcal{T}_h} h_T^3 \|\nabla(\Delta w - \mathbb{Q}_h \Delta w)\|_{\partial T}^2 \right)^{\frac{1}{2}} \left(\sum_{T \in \mathcal{T}_h} h_T^{-3} \|[e_h]\|_{\partial T}^2 \right)^{\frac{1}{2}} \\
 &\leq Ch^2 \|w\|_4 \left(\|\epsilon_h\| + \left(\sum_{T \in \mathcal{T}_h} h_T^{-3} \|[Q_h u - u]\|_{\partial T}^2 \right)^{\frac{1}{2}} \right) \\
 &\leq Ch^2 \|w\|_4 \left(\|e_h\| + \|Q_h u - u\| + \left(\sum_{T \in \mathcal{T}_h} h_T^{-3} \|[Q_h u - u]\|_{\partial T}^2 \right)^{\frac{1}{2}} \right) \\
 &\leq Ch^{k+1} \|u\|_{k+1} \|w\|_4.
 \end{aligned}$$

Similarly, we obtain

$$I_6 \leq Ch^{k+1} \|u\|_{k+1} \|w\|_4.$$

Combining all the estimates above yields

$$\|e_h\|^2 \leq Ch^{k+1-\delta_{k,2}} \|u\|_{k+1} \|w\|_4.$$

It follows from the above inequality and the regularity assumption (43).

$$\|e_h\| \leq Ch^{k+1-\delta_{k,2}} \|u\|_{k+1}.$$

We have completed the proof. □

7. Numerical Experiments

We solve the following biharmonic equation by P_k conforming DG finite element methods:

$$(45) \quad \Delta^2 u = f, \quad (x, y) \in \Omega = (0, 1)^2,$$

with the boundary conditions $u = g_1$ and $\nabla u \cdot \mathbf{n} = g_2$ on $\partial\Omega$. We choose f, g_1 and g_2 so that the exact solution is

$$u = e^{x+y}.$$

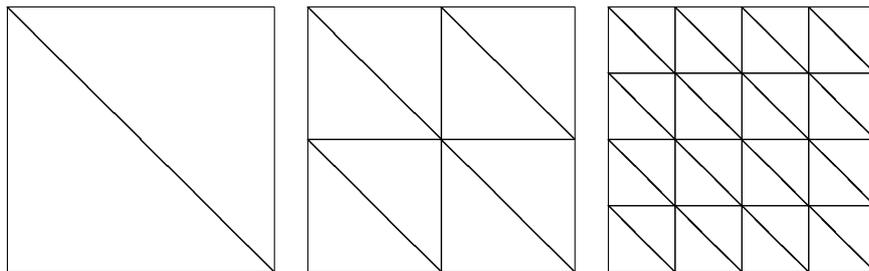


FIGURE 1. The first three levels of grids used in the computation of Table 1.

TABLE 1. The error and the order of convergence for (45) on triangular grids (Figure 1)

level	$\ u_h - u\ _0$	rate	$ u_h - u _{1,h}$	rate	$\ u_h - u\ $	rate
by the P_2 conforming DG finite element						
4	0.3653E-03	2.0	0.3281E-02	1.9	0.1229E+01	0.9
5	0.9566E-04	1.9	0.8733E-03	1.9	0.6312E+00	1.0
6	0.2480E-04	1.9	0.2268E-03	1.9	0.3199E+00	1.0
by the P_3 conforming DG finite element						
2	0.2291E-03	4.4	0.3275E-02	3.1	0.1612E+00	2.0
3	0.1143E-04	4.3	0.3889E-03	3.1	0.4577E-01	1.8
4	0.7148E-06	4.0	0.4743E-04	3.0	0.1243E-01	1.9

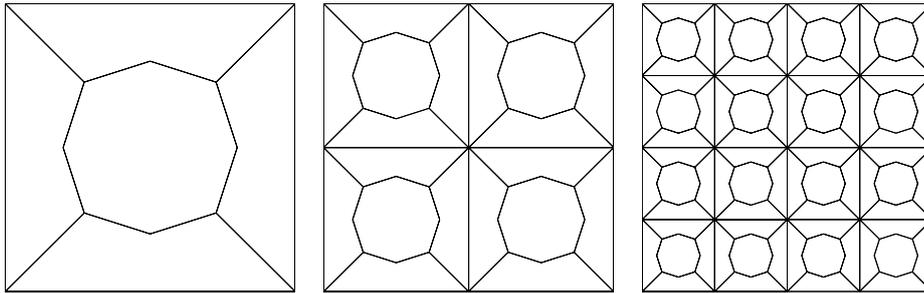


FIGURE 2. The first three polygonal grids for the computation of Table 2.

TABLE 2. Error profiles and convergence rates for (45) on polygonal grids (Figure 2)

level	$\ u_h - u\ _0$	rate	$ u_h - u _{1,h}$	rate	$\ u_h - u\ $	rate
by the P_2 conforming DG finite element						
4	0.3171E-03	1.9	0.4537E-02	1.9	0.3286E+01	1.0
5	0.8671E-04	1.9	0.1175E-02	1.9	0.1647E+01	1.0
6	0.2428E-04	1.8	0.3023E-03	2.0	0.8243E+00	1.0
by the P_3 conforming DG finite element						
1	0.3402E-02	0.0	0.3868E-01	0.0	0.3702E+01	0.0
2	0.2027E-03	4.1	0.4895E-02	3.0	0.9408E+00	2.0
3	0.1476E-04	3.8	0.6244E-03	3.0	0.2368E+00	2.0

In the first computation, the first three levels of grids are plotted in Figure 1. The error and the order of convergence for the method are listed in Tables 1. Here on triangular grids, we compute the weak Laplacian $\Delta_w v$ by P_{k+2} polynomials. The numerical results confirm the convergence theory.

In the next computation, we use a family of polygonal grids (with pentagons and of 8-side polygons) shown in Figure 2. We note that the polygons in meshes of Figure 2 are not convex. In the analysis, we assume convex polygons for simplicity only. The theory can be extended to cover such non-convex but good-shape polygons. We let the polynomial degree $j = k + 3$ for the weak Laplacian on such polygonal meshes. The rate of convergence is listed in Table 2. The convergence history confirms the theory.

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