2D Incompressible Euler Equation Linearized at Shear Flows: An Introduction

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Xiao Liu (Georgia Institute of Technology) 2D Incompressible Euler Equation Linearized

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Outline

1 2D Euler Equation Linearized at Shear Flows

Classical Results

- Howard's Semicircle Theorem
- Rayleigh Necessary Condition

3 Linear Instability Arising from Inflection Value

4 Linear Inviscid Damping of Couette Flow

2D Incompressible Euler Equation

• 2D incompressible Euler equation in a fixed channel $x = (x_1, x_2) \in \underline{\Omega} := \underline{\mathbb{T}}_L \times (0, 1), \ \underline{\mathbb{T}}_L = \mathbb{R} \setminus L\mathbb{Z}.$ $v = (v_1, v_2)(t, x) \in \mathbb{R}^2$: velocity, $p = p(t, x) \in \mathbb{R}$: pressure.

$$\begin{cases} \partial_t v + v \cdot \nabla v + \nabla p = 0, & x \in \Omega \\ \nabla \cdot v = 0, & x \in \Omega \\ v_2(x_2 = 0, 1) = 0. \end{cases}$$

- Shear flows: $v_* = (U(x_2), 0), p_* \equiv 0.$
- Question: Stability of this shear flow?

Linearized at Shear Flows

Linearize at shear flows:

$$\begin{cases} \partial_t v_2 + U(x_2)\partial_{x_1}v_2 + \partial_{x_2}p = 0, & x \in \Omega \\ \triangle p = -2U'(x_2)\partial_{x_2}v_2, & x \in \Omega \\ \partial_{x_2}p|_{x_2=0,1} = 0, \\ v_2(x_2 = 0, 1) = 0. \end{cases}$$

• Seek an unstable solution in the form:

$$v_2(t, x_1, x_2) = e^{ik(x_1-ct)}y(c, k, x_2) + c.c.$$

 $k \in \mathbb{Z}$: wave number, $c = c_R + ic_I \in \mathbb{C}$: wave speed. $k > 0, c_I > 0$

Eigenvalue Problem

• Rayleigh equation:

$$-y''(x_2) + (k^2 + rac{U''(x_2)}{U(x_2) - c})y(x_2) = 0, \qquad x_2 \in (0, 1)$$

w/ fixed boundary condition:

$$y(0)=y(1)=0.$$

 $\triangleright y \longleftrightarrow \text{ vertical component.}$ $<math display="block"> \triangleright \lambda = -ikc: \text{ eigenvalue.} \\ \triangleright (c, k > 0), c_l > 0: \text{ unstable mode.}$

When
$$c \notin U([\underbrace{-h, 0}])$$
, let ψ be $y(x_2) = (U(x_2) - c)\psi(x_2)$.

$$\begin{cases}
-y''(x_2) + (k^2 + \frac{U''(x_2)}{U(x_2) - c})y(x_2) = 0, & x_2 \in (0, 1) \\
y(0) = y(1) = 0.
\end{cases}$$

$$\left\{ egin{array}{ll} ((U-c)^2\psi')'-k^2(U-c)^2\psi=0, & x_2\in(0,1)\ \psi(0)=\psi(1)=0. \end{array}
ight.$$

- Howard's semicircle theorem
- No neutral mode, i.e. $(c,k), c \in \mathbb{R}$, w/ $c \in \mathbb{R} \setminus U([0,1])$.

• Howard's Semicircle Theorem:



$$(c_R - rac{U_{max} + U_{min}}{2})^2 + c_l^2 \leq (rac{U_{max} - U_{min}}{2})^2, \ \ ext{if} \ \ c_l > 0.$$

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Proof. $c_1 > 0$. Let ψ be $y(x_2) = (U(x_2) - c)\psi(x_2)$.

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$$((U-c)^2\psi')'-k^2(U-c)^2\psi=0, \quad \psi(0)=\psi(1)=0.$$

$$\int_0^1 \left(((U-c)^2 \psi')' - k^2 (U-c)^2 \psi \right) \overline{\psi} dx_2 = 0.$$

$$\int_0^1 (U-c)^2 (|\psi'|^2 + k^2 |\psi|^2) dx_2 = 0.$$

Let $Q := |\psi'|^2 + k^2 |\psi|^2 \ge 0$.

$$\int_0^1 (U-c)^2 Q dx_2 = 0.$$

Imaginary:

$$\int_{0}^{1} -2c_{I}(U-c_{R})Q = 0 \Rightarrow \int_{0}^{1} UQdx_{2} = c_{R}\int_{0}^{1} Qdx_{2}.$$

Real:

$$\int_0^1 ((U-c_R)^2 - c_I^2) Q dx_2 = 0 \Rightarrow \int_0^1 U^2 Q dx_2 = (c_R^2 + c_I^2) \int_0^1 Q dx_2.$$

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Consider $\int_0^1 (U - U_{max}) (U - U_{min}) Q dx_2 \le 0.$

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Real:

$$\int_{0}^{1} ((U - c_{R})^{2} - c_{I}^{2})Qdx_{2} = 0 \Rightarrow \int_{0}^{1} U^{2}Qdx_{2} = (c_{R}^{2} + c_{I}^{2})\int_{0}^{1} Qdx_{2}.$$
Consider $\int_{0}^{1} (U - U_{max})(U - U_{min})Qdx_{2} \leq 0.$

$$\int_{0}^{1} U^{2}Q - (U_{max} + U_{min})UQ + U_{max}U_{min}Qdx_{2} \leq 0.$$

$$\int_0^1 (U-c)^2 Q dx_2 = 0.$$

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Consider $\int_{0}^{1} (U - U_{max})(U - U_{min})Qdx_{2} \leq 0.$

$$\int_{0}^{1} U^{2}Q - (U_{max} + U_{min})UQ + U_{max}U_{min}Qdx_{2} \leq 0.$$

$$\int_{0}^{1} \left((c_{R} - \frac{U_{max} + U_{min}}{2})^{2} + c_{I}^{2} - (\frac{U_{max} - U_{min}}{2})^{2} \right)Qdx_{2} \leq 0.$$

† neutral mode: (c, k), $c \in \mathbb{R}$.

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$$y(x_2) = (U(x_2) - c)\psi(x_2).$$

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 ψ satisfies

$$\int_0^1 (U - c)^2 (|\psi'|^2 + k^2 |\psi|^2) dx_2 = 0.$$

$$c \in \mathbb{R} \setminus U([0,1]) \Longrightarrow \psi \equiv 0.$$



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$$\int_0^1 \Big(-y''(x_2) + (k^2 + \frac{U''(x_2)}{U(x_2) - c})y(x_2)\Big)\overline{y(x_2)}dx_2 = 0.$$

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(0) = y(1) = 0 \Longrightarrow
$$\int_0^1 |y'(x_2)|^2 + (k^2 + \frac{U''(x_2)(U(x_2) - c_R + ic_I)}{|U(x_2) - c|^2})|y(x_2)|^2 dx_2 = 0.$$

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Imaginary part:

$$c_{I}\int_{0}^{1}\frac{U''(x_{2})}{|U(x_{2})-c|^{2}}|y(x_{2})|^{2}dx_{2}=0.$$

Seek Unstable Eigenvalues $\begin{pmatrix} -\frac{d^{1}}{dx^{2}} + \frac{U''}{U-c} & = -k^{2}y \\ -y''(x_{2}) + (k^{2} + \frac{U''(x_{2})}{U(x_{2})-c})y(x_{2}) = 0, \quad x_{2} \in (0,1) \\ y(0) = y(1) = 0.$

- Treat k as a parameter.
 - No eigenvalue $\forall k \gg 1$.
- Continuation argument:
 - No eigenvalue w/ $c \in \mathbb{R} \setminus U([0,1])$
 - Semicircle theorem
 - Analyticity in $c \in \mathbb{C} \setminus U([0,1])$.

 \dagger neutral limiting mode ($c_* \in \mathbb{R}, k_*, y_*$): limit of unstable modes.

- Rayleigh necessary condition.
- $c = U_s$: inflection value of U.

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Seek Unstable Eigenvalues

Questions:

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- Existence of neutral mode at $c = U_s$?
 - Class \mathcal{K}^+ : U has exactly one inflection value U_s ,

$$K(x_2) := -\frac{U''(x_2)}{U(x_2) - U_s}, \text{ bounded}$$

e.g. $sin(mx_2), cos(mx_2).$
• $-k^2$: an eigenvalue of $-\frac{d^2}{dx_2^2} - K(x_2).$
Let

$$-k_{max}^{2} = \inf_{y \in H_{0}^{1}(0,1)} \frac{\int_{0}^{1} \left(|y'|^{2} - K(x_{2})|y|^{2} \right) dx_{2}}{\int_{0}^{1} |y|^{2} dx_{2}}$$

Seek Unstable Eigenvalues

Questions:

- Bifurcation of instability from $(c = U_s, k_{max})$?
- Linear instability when $k > k_{max}$ or $k < k_{max}$?
 - ► No eigenvalues for large k.
- Continuation of bifurcation curve?
 - ▶ $k \in (0, k_{max})?$

Linear Instability Arising from Inflection Value

Theorem (Lin, 2003)

If $U \in \mathcal{K}^+$, then

- for any neutral limiting mode (c_s, k_s, y_s) with k_s > 0, c_s must be U_s and y_s solves system Rayleigh system with U_s, k_s,
- $\exists \epsilon_0 < 0 \text{ s.t. for all } \epsilon \in (\epsilon_0, 0)$, there exists an unstable mode $(U_s + c(\epsilon), \sqrt{k_s^2 + \epsilon}, y_\epsilon)$,
- for all $k \in (0, k_{max})$, there is an unstable mode.

Idea of Proof

•
$$c_s = U_s$$
.
 $(-y'' + k^2y)(U-c) + U''y = 0.$

- $||y_n||_2 \leq C$, where $\{y_n\}_n$: unstable solutions w/ $\{(c_n, k_n)\}_n$.
- $y(x_{20}) \neq 0$, where $U(x_{20}) = c_s$.
- Seek unstable modes in a cone.

y(0)=0, y'(0)=1y(0, (.)) Couette Flow $U(x_2) = x_2$

• Eigenvalue problem
$$\iff \begin{cases} -y''(x_2) + k^2 y(x_2) = 0, \\ y(0) = y(1) = 0. \end{cases}$$

 \dagger Only trivial solution \Rightarrow spectrally stable

•
$$\partial_t \omega + \mathbf{v} \cdot \omega = \mathbf{0} \stackrel{\text{linearize}}{\longrightarrow} \partial_t \omega + \mathbf{x}_2 \partial_{\mathbf{x}_1} \omega = \mathbf{0}.$$

$$egin{aligned} &\omega(t,x_1,x_2) = &\omega^0(x_1-tx_2,x_2), \ &= \sum_{k\in\mathbb{Z}} e^{ikx_1} e^{-ikx_2t} \omega_k^0(x_2). \end{aligned}$$

Continuous spectrum: $[0, k] \rightarrow$ inviscid damping.

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Theorem (Lin-Zeng, 2011)
$$\int_{0}^{1} V_{1}^{0} dy_{1} = 0$$
.
Assume " $\int_{0}^{1} \omega^{0}(x_{1}, x_{2}) dx_{1} = 0$." Let $\omega(t, x_{1}, x_{2})$ be the solution of
 $\partial_{t}\omega + x_{2}\partial_{x_{1}}\omega = 0$ with $\omega(t = 0) = \omega^{0}(x_{1}, x_{2})$.
If $\omega^{0}(x_{1}, x_{2}) \in H_{x_{1}}^{-1}H_{x_{2}}^{1}$, then
 $\|\vec{v}\|_{L^{2}_{x}} = O(\frac{1}{t})$, when $t \to \infty$
If $\omega^{0}(x_{1}, x_{2}) \in H_{x_{1}}^{-1}H_{x_{2}}^{2}$, then
 $\|v_{2}\|_{L^{2}_{x}} = O(\frac{1}{t^{2}})$, when $t \to \infty$.

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Couette Flow (Linear Inviscid Damping)

$$S':= \int \phi(f|_{X_{1}X_{1}}) \quad \phi = \begin{bmatrix} C_{1} & X = 0 \\ C_{1} & X = 1 \end{bmatrix}.$$
Proof. (1) $S = \{\phi \in H^{1}_{X_{1}X_{2}} | \phi = 0 \text{ on } \{x_{2} = 0, 1\}\}. \quad \nabla^{\perp}\phi = \Gamma.$

$$\int_{0}^{1} \partial_{t} V_{1} + \bigvee \nabla V_{1} + \partial_{x_{1}} P dx_{1} = 0 \quad \Rightarrow \quad \forall f \int_{0}^{1} V_{1} dx_{1} = 0$$

$$\|\vec{v}\|_{L^{2}_{x}} \leq C \sup_{\phi \in S, \|\Gamma\|_{L^{2}} \leq 1} \int_{0}^{1} \int_{0}^{1} \vec{v} \cdot \Gamma dx_{2} dx_{1} \quad \int_{0}^{1} V_{1} dx_{1} = 0$$

$$\Rightarrow \phi = C \quad x_{2} = 0.2$$

Proof. (1)
$$S := \{ \phi \in H^1_{x_1 x_2} | \phi = 0 \text{ on } \{x_2 = 0, 1\} \}.$$
 $\nabla^{\perp} \phi = \Gamma.$

$$\begin{aligned} \|\vec{v}\|_{L^{2}_{x}} &\leq C \sup_{\phi \in S, \|\Gamma\|_{L^{2}} \leq 1} \int_{0}^{1} \int_{0}^{1} \vec{v} \cdot \Gamma dx_{2} dx_{1} \\ &\leq C \sup_{\phi \in S, \|\phi\|_{H^{1}_{0}} \leq 1} \int_{0}^{1} \int_{0}^{1} \phi \omega dx_{2} dx_{1} \end{aligned}$$

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Proof. (1)
$$S := \{ \phi \in H^1_{x_1 x_2} | \phi = 0 \text{ on } \{x_2 = 0, 1\} \}. \nabla^\perp \phi = \Gamma.$$

$$\| \vec{v} \|_{L^2_x} \le C \sup_{\phi \in S, \| \Gamma \|_{L^2} \le 1} \int_0^1 \int_0^1 \vec{v} \cdot \Gamma dx_2 dx_1$$
$$\le C \sup_{\phi \in S, \| \phi \|_{H^1_0} \le 1} \int_0^1 \int_0^1 \phi \omega dx_2 dx_1$$
$$= C \sup_{\phi \in S, \| \phi \|_{H^1_0} \le 1} \sum_{k \ne 0} | \int_0^1 \omega_k^0 \phi_{-k}(x_2) e^{-itkx_2} dx_2 |$$

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Proof. (1)
$$S := \{ \phi \in H^1_{x_1 x_2} | \phi = 0 \text{ on } \{x_2 = 0, 1\} \}. \nabla^{\perp} \phi = \Gamma.$$

 $\| \vec{v} \|_{L^2_x} \leq C \sup_{\phi \in S, \| \Gamma \|_{L^2} \leq 1} \int_0^1 \int_0^1 \vec{v} \cdot \Gamma dx_2 dx_1$
 $\leq C \sup_{\phi \in S, \| \phi \|_{H^1_0} \leq 1} \int_0^1 \int_0^1 \phi \omega dx_2 dx_1$
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 $= C \sup_{\phi \in S, \| \phi \|_{H^1_0} \leq 1} \sum_{k \neq 0} | \frac{1}{k} \int_0^1 \frac{d}{dx_2} (\omega_k^0(x_2) \phi_{-k}(x_2)) e^{-itkx_2} dx_2 |$

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$$\begin{aligned} \|\vec{v}\|_{L^{2}_{x}} &\leq \frac{C}{t} \sup_{\|\phi\|_{H^{1}_{0}} \leq 1} \left(\sum_{k \neq 0} \frac{1}{k^{2}} \left\| \omega^{0}_{k}(x_{2}) \right\|^{2}_{H^{1}_{x_{2}}} \right)^{1/2} \left(\sum_{k} \|\phi_{-k}\|^{2}_{H^{1}_{x_{2}}} \right)^{1/2} \\ &\leq \frac{C}{t} \left\| \omega^{0} \right\|_{H^{-1}_{x_{1}} H^{1}_{x_{2}}}. \end{aligned}$$

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(2) Let ψ be the solution of $\begin{cases} -\triangle \psi = \mathbf{v}_2, \\ \psi = \mathbf{0}. \quad \partial \Omega \end{cases}$

$$\|v_2\|_{L^2_x}^2 = \int_0^1 \int_0^1 \overline{v_2} v_2 dx_2 dx_1$$

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= $\int_0^1 \int_0^1 \overline{\psi} \partial_{x_1} \omega^0 (x_1 - tx_2, x_2) dx_2 dx_1$

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(2) Let ψ be the solution of $\begin{cases} -\triangle \psi = \mathbf{v}_2, \\ \psi = \mathbf{0}. \quad \partial \Omega \end{cases}$

$$\begin{aligned} \|v_2\|_{L^2_x}^2 &= \int_0^1 \int_0^1 \overline{v_2} v_2 dx_2 dx_1 = \int_0^1 \int_0^1 -\Delta \overline{\psi} v_2 dx_2 dx_1 \\ &= \int_0^1 \int_0^1 \overline{\psi} \partial_{x_1} \omega^0 (x_1 - tx_2, x_2) dx_2 dx_1 \\ &= \sum_{k \neq 0} \int_0^1 \overline{\psi_{-k}} i k e^{-iktx_1} \omega_k^0 (x_2) dx_2 \end{aligned}$$

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$$\|v_2\|_{L^2_x}^2 = \sum_{k\neq 0} \frac{1}{it^2k} \left(e^{-itkx_2} \frac{d}{dx_2} (\overline{\psi_{-k}}\omega_k^0)|_0^1 - \int_0^1 \frac{d^2}{dx_2^2} (\overline{\psi_{-k}}\omega_k^0) e^{-iktx_2} dx_2 \right)$$

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$$\begin{aligned} \|v_2\|_{L^2_x}^2 &= \sum_{k \neq 0} \frac{1}{it^2 k} \Big(e^{-itkx_2} \frac{d}{dx_2} (\overline{\psi_{-k}} \omega_k^0)|_0^1 - \int_0^1 \frac{d^2}{dx_2^2} (\overline{\psi_{-k}} \omega_k^0) e^{-iktx_2} dx_2 \Big) \\ &\leq C \sum_{k \neq 0} \frac{1}{t^2 |k|} \left\| \overline{\psi_k} \omega_k^0 \right\|_{H^2_{x_2}} \leq C \sum_{k \neq 0} \frac{1}{t^2 |k|} \left\| \psi_k \right\|_{H^2_{x_2}} \left\| \omega_k^0 \right\|_{H^2_{x_2}} \end{aligned}$$

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$$\begin{split} \|v_2\|_{L^2_x}^2 &= \sum_{k \neq 0} \frac{1}{it^2 k} \Big(e^{-itkx_2} \frac{d}{dx_2} (\overline{\psi_{-k}} \omega_k^0) |_0^1 - \int_0^1 \frac{d^2}{dx_2^2} (\overline{\psi_{-k}} \omega_k^0) e^{-iktx_2} dx_2 \Big) \\ &\leq C \sum_{k \neq 0} \frac{1}{t^2 |k|} \|\overline{\psi_k} \omega_k^0\|_{H^2_{x_2}} \leq C \sum_{k \neq 0} \frac{1}{t^2 |k|} \|\psi_k\|_{H^2_{x_2}} \|\omega_k^0\|_{H^2_{x_2}} \\ &\leq \frac{C}{t^2} \sum_{k \neq 0} \frac{1}{|k|} \|v_{2k}\|_{L^2_{x_2}} \|\omega_k^0\|_{H^2_{x_2}} \\ &\leq \frac{C}{t^2} \|\omega^0\|_{H^{-1}_{x_1} H^2_{x_2}} \|v_2\|_{L^2_{x_2}} \end{split}$$

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Thank you for your attention!

Xiao Liu (Georgia Institute of Technology) 2D Incompressible Euler Equation Linearized

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