

LECTURE 02 INTRODUCTION (CONT.), THE SIMPLEST DE

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Introduction (cont.).

	Analytic	Geometric
Differential Equations	Something like $y' = f(x, y)$	A Slope field: Short line segment at <i>every</i> point of the x - y plane with slope $f(x, y)$ at point (x, y) .
A solution:	A function $y(x)$ such that when replacing every y in the equation, makes the equation <i>identity</i> .	A curve that, at every point it passes, is tangent to the above short line segment.

Table 1. Analytic and Geometric Points of View for Differential Equations

- General solution of a differential equation: A formula involving constants, such that
 1. Whatever values we assign to these constants, we get a solution to the equation.
 2. The number of constants is the same as the order of the equation.
- “Solve the DE” = Find general solution.

Example 1. Which of the following are correct?

Solve the differential equation

$$y'' + 5y' + 4y = 0. \tag{1}$$

- Answer 1: $y = e^{-4x}$;
- Answer 2: $y = C_1 e^{-4x} + C_2 e^{-x}$;
- Answer 3: $y = C_1 e^{-4x} + C_2 (3e^{-4x})$.

Solution. Answer 2 is correct. Answer 1 does not have the correct number of arbitrary constants. Answer 3 seems to have two constants, but in fact has only one:

$$C_1 e^{-4x} + C_2 (3e^{-4x}) = (C_1 + 3C_2) e^{-4x}. \tag{2}$$

Remark 2. The reason that Answer 3 is not correct is that $3e^{-4x}$ is a multiple of e^{-4x} , so they are effectively the same thing when considering linear combinations with arbitrary coefficients.

The mathematical jargon for this situation is: e^{-4x} and $3e^{-4x}$ are **linearly dependent**. The real mathematical definition is the following:

Two functions f, g are linearly dependent if there are constants a, b , **not both zero**, such that $a f(x) + b g(x) = 0$ for all x of interest.¹

It is clear that this definition can be generalized to the case of three, four, or more functions. When writing general solutions of the form

$$y(x) = C_1 y_1(x) + C_2 y_2(x) + \dots + C_n y_n(x). \tag{3}$$

We need to make sure that y_1, y_2, \dots, y_n are **linearly independent** (= not linearly dependent).

More on this issue later.

1. This enables us to talk meaningfully about things like “ f, g are linearly dependent over the interval $[0, 1]$ ”.

- Boundary value and initial value problems.
 - Differential equations model real world phenomena. The solution tells us how a particle moves, how the price changes, etc. In reality there are no “arbitrary constants”. The particle moves along a certain path, the price change gives one specific graph, etc.
 - There are extra conditions in real world phenomena. For example, to determine the path of a particle, we not only require that the particle is subject to Newton’s law, we also specify “initial conditions”: Where is this particle at the initial time? What is its velocity then?
 - In the abstract mathematical model this is equivalent to require:

$$\ddot{x} = f, \quad x(0) = x_0, \quad \dot{x}(0) = v_0. \quad (4)$$

- Technical definition:
 - Initial value problem (IVP): DE + extra conditions at one single point;
 - Boundary value problem (BVP): DE + extra conditions at at least two different points.
- Examples:

$$y'' + 9y' + 8y = 0; \quad y(0) = y'(0) = 0: \quad (\text{IVP}) \quad (5)$$

$$y''' + 8y'' + 3y = 0; \quad y(0) = 1, y'(1) = 2, y''(2) = 3: \quad (\text{BVP}) \quad (6)$$

From the simplest to the mother of all DEs.

- The simplest DE that can be solved by anyone after Calculus I:

$$y' = f(x). \quad (7)$$

Just integrate to get general solution (don’t forget the constant!)

$$y = F(x) + C. \quad (8)$$

Reason: The equation is no other than

$$(y - F(x))' = 0. \quad (9)$$

So the solution is given by

$$y - F(x) = C. \quad (10)$$

- After Calculus II or III, we can write $(y - F(x))' = 0$ as $d(y - F(x)) = 0$. As we know that

$$du(x, y) = 0 \iff u(x, y) = C \quad (11)$$

we can solve the following equations:

$$d(xy) = 0 \implies xy = C \implies y = \frac{C}{x}. \quad (12)$$

$$d(x^2 y^3) = 0 \implies x^2 y^3 = C. \quad (13)$$

- Explicit and implicit formulas of the solution.
 - $y = \frac{C}{x}$ is an explicit formula of the solution y ;
 - $x^2 y^3 = C$ is an implicit formula of the solution y .

Rule of thumb: When it’s impossible or not worthwhile to get explicitly $y = \dots$, we just write the solution in its implicit form. (**Warning**: whether it’s “worthwhile” is different for different people!)

Example 3.

- $xy = C$: Easy. Should write $y = \frac{C}{x}$;
- $\tan y - y - x^2 = C$: Impossible. Just leave like that.
- $y^4 + 3xy^2 - 2y + 5x = C$: Not worthwhile. Just leave like that.

- $x^2 y^3 = C$: Borderline, but on the “easy” side.
- In this class, for borderline cases, I will treat both explicit and implicit formulas as OK.
- The problem is that no equation is given in the form $d(u(x, y)) = 0$. Usually they are given either like $y' = f(x, y)$ or $M(x, y) dx + N(x, y) dy = 0$.
 - The two forms are roughly equivalent. As

$$y' = f(x, y) \iff \frac{dy}{dx} = f(x, y) \iff -f(x, y) dx + dy = 0. \quad (14)$$

$$M(x, y) dx + N(x, y) dy = 0 \iff N(x, y) \frac{dy}{dx} = -M(x, y) \approx y' = -\frac{M(x, y)}{N(x, y)}. \quad (15)$$

The last \approx is because dividing by $N(x, y)$ in fact changes the equation. We will discuss this issue more in the following lectures.

- **How do we know whether a given $M(x, y) dx + N(x, y) dy = 0$ is the same as $du = 0$?** (When this happens, the equation is called “exact”.)
 - This is not always the case. (We will discuss a criterion to check this).
 - Turns out, all solution strategies for first order ODEs can be summarized as: Transform the equation to be exact.
 - Thus we have “jumped” from the simplest DE to the mother of all DEs.

5-min Quiz.

Problem 1. Solve $\dot{y} = t e^t$.

Solution. All we need to do is to find the primitive of $t e^t$. Calculate:

$$\begin{aligned} \int t e^t dt &= \int u dv \quad (u = t, v = e^t) \\ &= u v - \int v du \\ &= t e^t - \int e^t dt \quad (\text{Integration by parts}) \\ &= t e^t - e^t \\ &= e^t (t - 1). \end{aligned} \quad (16)$$

For those who are familiar with the integration by parts process, the step $u = t, v = e^t$ can be omitted. Just write

$$\int t e^t dt = \int t de^t = t e^t - \int e^t dt = t e^t - e^t = (t - 1) e^t. \quad (17)$$

Now write down the solution (**don't forget!**)

$$y = (t - 1) e^t + C. \quad (18)$$

The ability to evaluate integrals like $\int t^k e^t dt$, $\int t^k \sin t dt$, $\int e^t \sin t dt$ is important in solving differential equations.