# MINIMAL VECTORS IN ARBITRARY BANACH SPACES 

VLADIMIR G. TROITSKY


#### Abstract

We extend the method of minimal vectors to arbitrary Banach spaces. It is proved, by a variant of the method, that certain quasinilpotent operators on arbitrary Banach spaces have hyperinvariant subspaces.


The method of minimal vectors was introduced by Ansari and Enflo in [AE98] in order to prove the existence of invariant subspaces for certain classes of operators on a Hilbert space. Pearcy used it in $[\mathrm{P}]$ to prove a version of Lomonosov's theorem. Androulakis in [A] adapted the technique to super-reflexive Banach spaces. In [CPS] the method was independently generalized to reflexive Banach spaces. There has been hope that this technique could provide a positive solution to the invariant subspace problem for these spaces. In this note we present a version of the method of minimal vectors (based on [A]) that works for arbitrary Banach spaces. In particular, it applies in the spaces where there are known examples of operators without invariant subspaces, e.g., [Enf76, Enf87, Rea84, Rea85]. This shows that the method of minimal vectors alone cannot solve the invariant subspace problem for "good" spaces.

Suppose that $X$ is a Banach space. For simplicity, we assume that $X$ is a real Banach space, though the results can be adapted to the complex case in a straightforward manner. In the following, $B\left(x_{0}, \varepsilon\right)$ stands for the closed ball of radius $\varepsilon$ centered at $x_{0}$ while $B^{\circ}\left(x_{0}, \varepsilon\right)$ stands for the open ball, and $S\left(x_{0}, \varepsilon\right)$ stands for the corresponding sphere.

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Let $Q$ be a bounded operator on $X$. Since we will be interested in the hyperinvariant subspaces of $Q$, we can assume, without loss of generality, that $Q$ is one-to-one and has dense range, since otherwise ker $Q$ or $\overline{\operatorname{Range} Q}$ would be hyperinvariant for $Q$. By $\{Q\}^{\prime}$ we denote the commutant of $Q$.

Fix a point $x_{0} \neq 0$ in $X$ and a positive real $\varepsilon<\left\|x_{0}\right\|$. Let $K=$ $Q^{-1} B\left(x_{0}, \varepsilon\right)$. Clearly, $K$ is a convex closed set. Note that $0 \notin K$ and $K \neq \varnothing$ because $Q$ has dense range. Let $d=\inf _{K}\|z\|$. Then $d>0$. It is observed in [AE98, A] that if $X$ is reflexive, then there exists $z \in K$ with $\|z\|=d$. Such a vector is called a minimal vector for $x_{0}, \varepsilon$ and $Q$. Even without the reflexivity condition, however, one can always find $y \in K$ with $\|y\| \leqslant 2 d$; such a $y$ will be referred to as a 2-minimal vector for $x_{0}, \varepsilon$ and $Q$.

The set $K \cap B(0, d)$ is the set of all minimal vectors; in general, this set may be empty. If $z$ is a minimal vector, since $z \in K=Q^{-1} B\left(x_{0}, \varepsilon\right)$ then $Q z \in B\left(x_{0}, \varepsilon\right)$. Since $z$ is an element of minimal norm in $K$, then, in fact, $Q z \in S\left(x_{0}, \varepsilon\right)$. Since $Q$ is one-to-one, we have

$$
Q B(0, d) \cap B\left(x_{0}, \varepsilon\right)=Q(B(0, d) \cap K) \subseteq S\left(x_{0}, \varepsilon\right)
$$

It follows that $Q B(0, d)$ and $B^{\circ}\left(x_{0}, \varepsilon\right)$ are two disjoint convex sets. Since one of them has nonempty interior, they can be separated by a continuous linear functional (see, e.g., [AB99, Theorem 5.5]). That is, there exists a functional $f$ with $\|f\|=1$ and a positive real $c$ such that $f_{\mid Q B(0, d)} \leqslant c$ and $f_{\mid B^{\circ}\left(x_{0}, \varepsilon\right)} \geqslant c$. By continuity, $f_{\mid B\left(x_{0}, \varepsilon\right)} \geqslant c$. We say that $f$ is a minimal functional for $x_{0}, \varepsilon$, and $Q$.

We claim that $f\left(x_{0}\right) \geqslant \varepsilon$. Indeed, for every $x$ with $\|x\| \leqslant 1$ we have $x_{0}-\varepsilon x \in B\left(x_{0}, \varepsilon\right)$. It follows that $f\left(x_{0}-\varepsilon x\right) \geqslant c$, so that $f\left(x_{0}\right) \geqslant c+\varepsilon f(x)$. Taking sup over all $x$ with $\|x\| \leqslant 1$ we get $f\left(x_{0}\right) \geqslant$ $c+\varepsilon\|f\| \geqslant \varepsilon$.

Observe that the hyperplane $Q^{*} f=c$ separates $K$ and $B(0, d)$. Indeed, if $z \in B(0, d)$, then $\left(Q^{*} f\right)(z)=f(Q z) \leqslant c$, and if $z \in K$, then $Q z \in B\left(x_{0}, \varepsilon\right)$ so that $\left(Q^{*} f\right)(z)=f(Q z) \geqslant c$. For every $z$ with $\|z\| \leqslant 1$ we have $d z \in B(0, d)$, so that $\left(Q^{*} f\right)(d z) \leqslant c$. It follows
that $\left\|Q^{*} f\right\| \leqslant \frac{c}{d}$. On the other hand, for every $\delta>0$ there exists $z \in K$ with $\|z\| \leqslant d+\delta$. Then $\left(Q^{*} f\right)(z) \geqslant c \geqslant \frac{c}{d+\delta}\|z\|$, whence $\left\|Q^{*} f\right\| \geqslant \frac{c}{d+\delta}$. It follows that $\left\|Q^{*} f\right\|=\frac{c}{d}$. For every $z \in K$ we have $\left(Q^{*} f\right)(z) \geqslant c=d\left\|Q^{*} f\right\|$. In particular, if $y$ is a 2-minimal vector, then

$$
\begin{equation*}
\left(Q^{*} f\right)(y) \geqslant \frac{1}{2}\left\|Q^{*} f\right\|\|y\| \tag{1}
\end{equation*}
$$

We proceed to the main theorem.
Theorem. Let $Q$ be a quasinilpotent operator on a Banach space $X$, and suppose that there exists a closed ball $B$ such that $0 \notin B$ and for every sequence $\left(x_{n}\right)$ in $B$ there is a subsequence $\left(x_{n_{i}}\right)$ and a sequence $\left(K_{i}\right)$ in $\{Q\}^{\prime}$ such that $\left\|K_{i}\right\| \leqslant 1$ and $\left(K_{i} x_{n_{i}}\right)$ converges in norm to a nonzero vector. Then $Q$ has a hyperinvariant subspace.

Remark. The hypothesis of the theorem is slightly weaker than the condition $(*)$ in $[\mathrm{A}]$, where it is required that for every $\varepsilon \in(0,1)$, there exists $x_{0}$ of norm one such that the ball $B\left(x_{0}, \varepsilon\right)$ satisfies the rest of the condition.

Proof. Without loss of generality, $Q$ is one-to-one and has dense range. Let $x_{0} \neq 0$ and $\varepsilon \in\left(0,\left\|x_{0}\right\|\right)$ be such that $B=B\left(x_{0}, \varepsilon\right)$. For every $n \geqslant 1$ choose a 2 -minimal vector $y_{n}$ and a minimal functional $f_{n}$ for $x_{0}, \varepsilon$, and $Q^{n}$.

Since $Q$ is quasinilpotent, there is a subsequence $\left(y_{n_{i}}\right)$ such that $\frac{\left\|y_{n_{i}-1}\right\|}{\left\|y_{n_{i}}\right\|} \rightarrow 0$. Indeed, otherwise there would exist $\delta>0$ such that $\frac{\left\|y_{n-1}\right\|}{\left\|y_{n}\right\|}>\delta$ for all $n$, so that $\left\|y_{1}\right\| \geqslant \delta\left\|y_{2}\right\| \geqslant \ldots \geqslant \delta^{n}\left\|y_{n+1}\right\|$. Since $Q^{n} y_{n+1} \in Q^{-1} B$, we have

$$
\left\|Q^{n} y_{n+1}\right\| \geqslant d \geqslant \frac{\left\|y_{1}\right\|}{2} \geqslant \frac{\delta^{n}}{2}\left\|y_{n+1}\right\| .
$$

It follows that $\left\|Q^{n}\right\| \geqslant \delta^{n} / 2$, which contradicts the quasinilpotence of $Q$.

Since $\left\|f_{n_{i}}\right\|=1$ for all $i$, we can assume (by passing to a further subsequence), that $\left(f_{n_{i}}\right)$ weak*-converges to some $g \in X^{*}$. Since $f_{n}\left(x_{0}\right) \geqslant \varepsilon$ for all $n$, it follows that $g\left(x_{0}\right) \geqslant \varepsilon$. In particular, $g \neq 0$.

Consider the sequence $\left(Q^{n_{i}-1} y_{n_{i}-1}\right)_{i=1}^{\infty}$. It is contained in $B$, so that by passing to yet a further subsequence, if necessary, we find a sequence $\left(K_{i}\right)$ in $\{Q\}^{\prime}$ such that $\left\|K_{i}\right\| \leqslant 1$ and $K_{i} Q^{n_{i}-1} y_{n_{i}-1}$ converges in norm to some $w \neq 0$. Put

$$
Y=\{Q\}^{\prime} Q w=\left\{T Q w \mid T \in\{Q\}^{\prime}\right\}
$$

One can easily verify that $Y$ is a linear subspace of $X$ invariant under $\{Q\}^{\prime}$. Notice that $Y$ is nontrivial because $Q$ is one-to-one and $0 \neq$ $Q w \in Y$. We will show that $Y \subseteq \operatorname{ker} g$, so that $\bar{Y}$ is a proper $Q$-hyperinvariant subspace.

Take $T \in\{Q\}^{\prime} ;$ we will show that $g(T Q w)=0$. It follows from (1) that $\left(Q^{* n_{i}} f_{n_{i}}\right)\left(y_{n_{i}}\right) \neq 0$ for every $i$, so that $X=\operatorname{span}\left\{y_{n_{i}}\right\} \oplus$ $\operatorname{ker}\left(Q^{* n_{i}} f_{n_{i}}\right)$. Then one can write $T K_{i} y_{n_{i}-1}=\alpha_{i} y_{n_{i}}+r_{i}$, where $\alpha_{i}$ is a scalar and $r_{i} \in \operatorname{ker}\left(Q^{* n_{i}} f_{n_{i}}\right)$. We claim that $\alpha_{i} \rightarrow 0$. Indeed,

$$
\begin{equation*}
\left(Q^{* n_{i}} f_{n_{i}}\right)\left(T K_{i} y_{n_{i}-1}\right)=\alpha_{i}\left(Q^{* n_{i}} f_{n_{i}}\right)\left(y_{n_{i}}\right) \tag{2}
\end{equation*}
$$

and, combining this with (1), we get

$$
\begin{equation*}
\left|\left(Q^{* n_{i}} f_{n_{i}}\right)\left(T K_{i} y_{n_{i}-1}\right)\right| \geqslant \frac{\left|\alpha_{i}\right|}{2}\left\|Q^{* n_{i}} f_{n_{i}}\right\|\left\|y_{n_{i}}\right\| \tag{3}
\end{equation*}
$$

On the other hand,

$$
\begin{equation*}
\left|\left(Q^{* n_{i}} f_{n_{i}}\right)\left(T K_{i} y_{n_{i}-1}\right)\right| \leqslant\left\|Q^{* n_{i}} f_{n_{i}}\right\| \cdot\|T\| \cdot\left\|y_{n_{i}-1}\right\| . \tag{4}
\end{equation*}
$$

It follows from (3) and (4) that

$$
\left|\alpha_{i}\right| \leqslant 2\|T\| \frac{\left\|y_{n_{i}-1}\right\|}{\left\|y_{n_{i}}\right\|} \rightarrow 0
$$

Then (2) yields that

$$
\begin{aligned}
& \left|f_{n_{i}}\left(Q^{n_{i}} T K_{i} y_{n_{i}-1}\right)\right|=\left|\alpha_{i} f_{n_{i}}\left(Q^{n_{i}} y_{n_{i}}\right)\right| \\
& \leqslant\left|\alpha_{i}\right| \cdot\left\|f_{n_{i}}\right\| \cdot\left\|Q^{n_{i}} y_{n_{i}}\right\| \leqslant\left|\alpha_{i}\right| \cdot 1 \cdot\left(\left\|x_{0}\right\|+\varepsilon\right) \rightarrow 0
\end{aligned}
$$

so that $f_{n_{i}}\left(Q^{n_{i}} T K_{i} y_{n_{i}-1}\right) \rightarrow 0$. On the other hand, since $T, K_{i} \in\{Q\}^{\prime}$ we have

$$
Q^{n_{i}} T K_{i} y_{n_{i}-1}=T Q K_{i} Q^{n_{i}-1} y_{n_{i}-1} \rightarrow T Q w
$$

in norm, while $f_{n_{i}} \xrightarrow{w^{*}} g$, so that $f_{n_{i}}\left(Q^{n_{i}} T K_{i} y_{n_{i}-1}\right) \rightarrow g(T Q w)$. Hence, $g(T Q w)=0$.

Clearly, the argument will work as well for $\lambda$-minimal vectors for any $\lambda>1$.

Suppose that $Q$ is a quasinilpotent operator commuting with a compact operator $K$. Then $Q$ satisfies the hypothesis of the theorem. Indeed, without loss of generality, $\|K\|=1$. Fixing $\varepsilon=\frac{1}{3}$, there exists $x_{0}$ with $\left\|x_{0}\right\|=1$ such that $\left\|K x_{0}\right\| \geqslant \frac{2}{3}$ and $0 \notin K B\left(x_{0}, \varepsilon\right)$. For every sequence $\left(x_{n}\right)$ in $B\left(x_{0}, \varepsilon\right)$, the sequence $\left(K x_{n}\right)$ has a convergent subsequence $\left(K x_{n_{i}}\right)$. Take $K_{i}=K$ for all $i$; since $0 \notin K B\left(x_{0}, \varepsilon\right)$ then $\lim _{i} K_{i} x_{n_{i}} \neq 0$. It follows from the theorem that if $Q$ is a quasinilpotent operator on a real or complex Banach space commuting with a nonzero compact operator, then $Q$ has a hyperinvariant subspace. This fact is not new though: for complex Banach spaces it is a special case of the celebrated Lomonosov's theorem [Lom73], and for real Banach spaces it follows from Theorem 2 of [Hoo81].

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Department of Mathematics, University of Alberta, Edmonton, AB, T6G 2G1. Canada.

E-mail address: vtroitsky@math.ualberta.ca

