

§5 Global Attractors

H Banach space, often Hilbert-space

$\{H, \{S(t)\}_{t \geq 0}\}$ a semidynamical system

$$(i) \quad S(0) = I, \quad S(t+s) = S(t)S(s)$$

$$(ii) \quad S(t)u_0 = u(t) \quad \text{is continuous in both } t \text{ and } u_0.$$

We call $S(t)$ a C^0 -semigroup.

It follows the uniform continuity on compact sets

(see Exercise 10.1): For each $K \subset H$ there exists a nondecreasing function $\delta_K(t, u)$ with

$$\delta_K(t, 0) = 0, \quad \delta_K(0, d) = d \quad \text{and}$$

$$|S(t)u_0 - S(t)v_0| \leq \delta_K(T, |u_0 - v_0|)$$

Now we use $|\cdot| = \|\cdot\|_H$, $\|\cdot\| = \|\cdot\|_V$

(5.1) Dissipation, Limit Sets and Attractors

Definition 1

a) A bounded set $B \subset H$ is attracting, if for each $x_0 \in H$ there is a $t_0(x_0)$ such that

$$S(t)x_0 \in B \quad \text{for all } t > t_0(x_0).$$

b) $S(t)$ is point-dissipative if H has an attracting set B .

- c) A bounded set $B \subset H$ is absorbing if it is attracting, and for each bounded set $X \subset H$ there is a time $t_1(X) > 0$ such that
- $$S(t)X \subset B \text{ for all } t \geq t_1(X).$$
- d) $S(t)$ is bounded dissipative, if H has an absorbing subset.
- e) $S(t)$ is dissipative, if H has a compact absorbing subset.
- f) $X \subset H$ is positively invariant, if $S(t)X \subset X$, $t \geq 0$
- g) $X \subset H$ is invariant, if $S(t)X = X$, $t \geq 0$.

Lemma 1: $H = \mathbb{R}^n$.

- (i) $S(t)$ point dissipative $\Leftrightarrow S(t)$ dissipative
- (ii) B attracting set, then for each $\varepsilon > 0$ the set

$$B_\varepsilon = \overline{\bigcup_{0 \leq t < \infty} S(t)(\overline{N}(B, \varepsilon))}$$

is absorbing.

Proof: clear: dissipative $\Rightarrow$ point dissipative.

Now assume $S(t)$ is point dissipative with attracting set B .

B_ε is bounded and closed (by construction)
hence compact.

Let $X \subset H$ be bounded. For each $z \in X$ there is a
 $t_0(z) > 0$ such that $S(t)z \in B_\varepsilon$ for all $t \geq t_0(z)$.

Since the flow is continuous there exists a
neighborhood $N(z)$ such that $S(t)N \subseteq N(B_\varepsilon)$
for all $t \geq t_0(z)$. $X \subset \mathbb{R}^n$ bounded, hence $\bar{X}$ is
compact. We take a finite subcover $\{N(z_i)\}_{i=1, \dots, m}$
and we choose $t^* = \max_{i=1, \dots, m} t_0(z_i)$.

Then $S(t)X \subset B_\varepsilon$ for all $t \geq t^*$.

□

Definition 2 ω -Limit sets of sets $X \subset H$:

$$\omega(X) = \{y: \text{exists } t_n \rightarrow \infty, x_n \in X: S(t_n)x_n \rightarrow y\}$$

$$= \bigcap_{t \geq 0} \overline{\bigcup_{s \geq t} S(s)X}$$

Lemma 2: $X \subset H$. If for some $t_0 > 0$ the set

$\bigcup_{t \geq t_0} S(t)X$ is compact, then $\omega(X)$ is

nonempty, compact and invariant.

Proof: For $t \geq t_0$ the sets $W_t := \overline{\bigcup_{s \geq t} S(s)X}$ are nonempty, compact and nested: $W_t \subset W_s$ for $t \geq s$. Hence their intersection $\omega(X) = \bigcap_{t \geq 0} W_t$ is nonempty and compact.

$S(t)\omega(X) \subset \omega(X)$: Let $y \in \omega(X)$, $\lim_{n \rightarrow \infty} S(t_n)x_n = y$

then $S(t)y = \lim_{n \rightarrow \infty} S(t+t_n)x_n = \lim_{n \rightarrow \infty} S(\sigma_n)x_n$, $\sigma_n = t+t_n$,
 $\in \omega(X)$.

$\omega(X) \subset S(t)\omega(X)$: Let $y \in \omega(X)$, $\lim_{n \rightarrow \infty} S(t_n)x_n = y$.

Study $t_n > t_0 + t$, then

$$\begin{aligned} y &= \lim_{n \rightarrow \infty} S(t_n)x_n = \lim_{n \rightarrow \infty} S(t)S(t_n-t)x_n \\ &= S(t) \lim_{n \rightarrow \infty} S(t_n-t)x_n \end{aligned}$$

Now $S(t_n-t)x_n$ converges, since $t_n-t > t_0$.

□

Suppose $S(t)$ is dissipative with absorbing set B .

Is $\omega(B)$ a good candidate for an attractor?

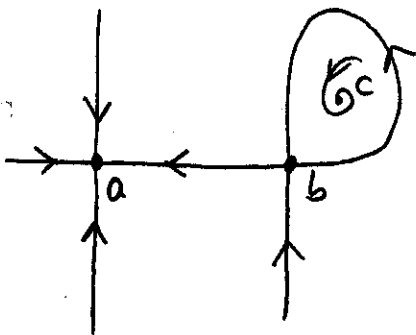
Definition The global attractor A is the maximal compact invariant set $S(t)A = A$ for all $t \geq 0$ and the minimal set that attracts all bounded sets, i.e.

$\text{dist}(S(t)X, A) \rightarrow 0$ as $t \rightarrow \infty$
for all $X \subset H$ bounded.

Q: How to find A :

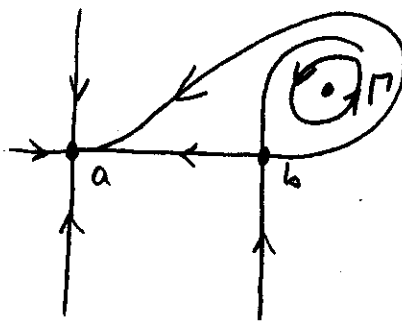
Candidate 1 $A := \bigcup_{x \in B} \omega(x)$

Examples



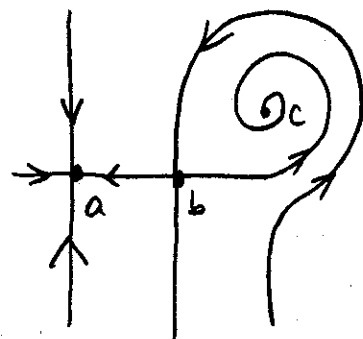
I

$$A_I = \{a, b, c\}$$



II

$$A_{II} = \{a, b, c, \Gamma\}$$



III

$$A_{III} = \{a, b, c\}$$

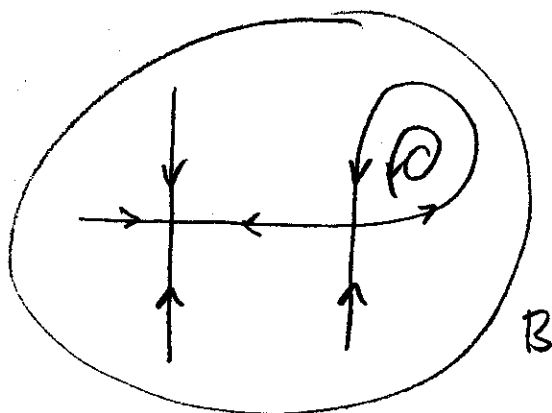
↑
"explosion" of the attractor.

But $A_I = \{a, b, c\}$ is not maximal invariant, because

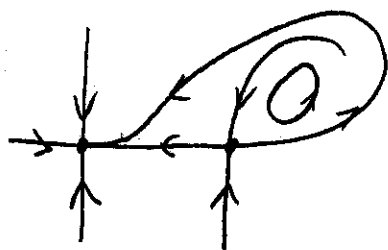
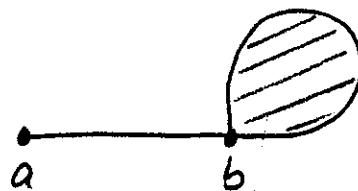
$$\tilde{A}_I = \left\{ \begin{array}{c} \bullet \longleftarrow \bullet \\ a \qquad b \end{array} \quad \cdot c \right\} \text{ is also invariant.}$$

Candidate 2

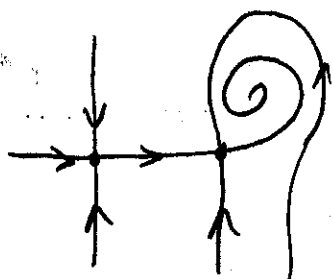
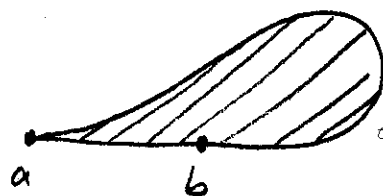
$$A = \omega(B).$$



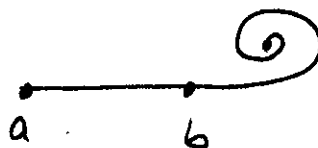
A_I



A_{II}



A_{III}



Theorem 1 $S(t)$ dissipative, B absorbing, then

$A = \omega(B)$ is the global attractor.

If H is connected, then A is connected.

Proof: (i) $\omega(B)$ is nonempty, compact and invariant (Lemma 2 in (5.1)).

(ii) $\omega(B)$ is the maximal compact invariant set.

If Y is also invariant, then $S(t)Y = Y$, $\omega(Y) = Y$ and $S(t)Y \subset B$ for all $t \geq t_0(X)$. Then $\omega(Y) \subset \omega(B)$.

(iii) To show that A attracts bounded sets we assume that there exists a bounded set X such that $\text{dist}(S(t_n)X, A) \geq \delta$ for $t_n \rightarrow \infty$.

There are points x_n : $\text{dist}(S(t_n)x_n, A) \geq \frac{\delta}{2}$
For t large enough $S(t)x_n \in B$ and B is cp.
Hence we find a convergent subsequence
 $S(t_{n_j})x_{n_j} \rightarrow \beta \in B$, and still $\text{dist}(\beta, A) \geq \frac{\delta}{2}$.

$$\beta = \lim_{j \rightarrow \infty} S(t_{n_j})x_{n_j} = \lim_{j \rightarrow \infty} S(t_{n_j} - t_0(X)) S(t_0(X))x_{n_j}$$

$\subset \omega(B) \quad \downarrow \text{contradiction.}$

(iv) A is the minimal set that attracts bounded sets and it is invariant.

Indeed, if there is a smaller set Γ then this would attract $\omega(B)$, hence $\omega(B) \subset \Gamma$. Since $\omega(B)$ is invariant we get $S(t)A = A$.

(v) A connected:

Suppose A is not connected. Then exists O_1, O_2 s.t.

$A \subset O_1 \cup O_2$, $A \cap O_1 \neq \emptyset$, $A \cap O_2 \neq \emptyset$, $O_1 \cap O_2 = \emptyset$.

Let U be a ball in H that covers B .

U is connected and $\omega(U) = \omega(B)$. Since $S(t)$ is continuous $S(t)U$ is connected. Hence for t large enough $S(t) \cap O_i \neq \emptyset$ for all $i=1,2$.

But $S(t)U \not\subset O_1 \cup O_2$. Then for each $t_n \rightarrow \infty$ we find $x_n \in U$, $S(t_n)x_n \notin O_1 \cup O_2$.

For $t_n > t_0(U)$ the sequence $S(t_n)x_n$ converges in B to $x_0 \notin O_1 \cup O_2$, but $x_0 \in A$ $\downarrow$

□

Definition: A semigroup is injective on A , if

$S(t)u_0 = S(t)v_0 \in A$ for some $t \geq 0$, then $u_0 = v_0$.

Theorem 2 If a semigroup $S(t)$ is injective on A

then each trajectory in A is global (i.e. defined for $t \in \mathbb{R}$). We have $S(t)A = A$ for all $t \in \mathbb{R}$

and $(A, \{S(t)\}_{t \in \mathbb{R}})$ is a dynamical system

Proof: For $u \in \omega(B)$ we know that $S(t)u \in \omega(B)$.

Since $S(t)$ is injective we find a unique

$v \in \omega(B)$ with $u = S(t)v$. We define

$S(-t)u = v$. By this definition we have

$S(0) = I$, $S(t+s) = S(t)S(s)$ for all $s, t \in \mathbb{R}$ on $\mathcal{X}$.

To show that $S(t)$ is continuous for $t < 0$,

we look at a sequence $u_n \rightarrow u$ in $\omega(B)$.

By the above definition we find $v_n = S(-t)u_n$

and $v = S(-t)u$, $v_n, v \in \omega(B)$ hence $\{v_n\}$ has

a convergent subsequence $v_{n_j} \rightarrow z$ with

$$S(t)z = S(t) \lim_j v_{n_j} = S(t) \lim_j S(-t)u_{n_j}$$

$$= \lim_j S(t-t)u_{n_j} = \lim_j u_{n_j} = u$$

Since $S(t)$ is injective we must have $z = v$,

hence $S(-t)u_n \rightarrow v = S(-t)u$

□.

Example: Lorenz equations

We showed a positively
invariant absorbing set

$$E = \{(x, y, z); V(x, y, z) \leq C + \varepsilon\}$$

$$V(x, y, z) = \mu x^2 + \sigma y^2 + \sigma(z - z_\mu)^2.$$

$$\begin{cases} \dot{x} = \sigma(y - x) \\ \dot{y} = \mu x - y - xz \\ \dot{z} = -\beta z + xy \end{cases}$$

$$\Rightarrow \mathcal{A} = \omega(E) \neq \emptyset.$$