Implicitly Dealiased Convolutions on Shared-Memory and Distributed-Memory Parallel Processors

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- The fast Fourier transform method exploits the properties that $\zeta_N^r = \zeta_{N/r}$ and $\zeta_N^N = 1$.
- However, the pseudospectral method requires a *linear* convolution.

• The unnormalized backwards discrete Fourier transform of $\{F_k : k = 0, \dots, N\}$ is

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• The orthogonality of this transform pair follows from

$$\sum_{j=0}^{N-1} \zeta_N^{\ell j} = \begin{cases} N & \text{if } \ell = sN \text{ for } s \in \mathbb{Z}, \\ \frac{1 - \zeta_N^{\ell N}}{1 - \zeta_N^{\ell}} = 0 & \text{otherwise.} \end{cases}$$

Convolution Theorem

$$\sum_{j=0}^{N-1} f_j g_j \zeta_N^{-jk} = \sum_{j=0}^{N-1} \zeta_N^{-jk} \left(\sum_{p=0}^{N-1} \zeta_N^{jp} F_p \right) \left(\sum_{q=0}^{N-1} \zeta_N^{jq} G_q \right)$$

$$= \sum_{p=0}^{N-1} \sum_{q=0}^{N-1} F_p G_q \sum_{j=0}^{N-1} \zeta_N^{(-k+p+q)j}$$

$$= N \sum_{s} \sum_{p=0}^{N-1} F_p G_{k-p+sN}.$$

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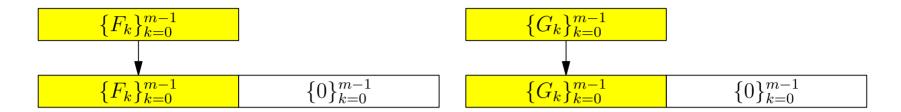
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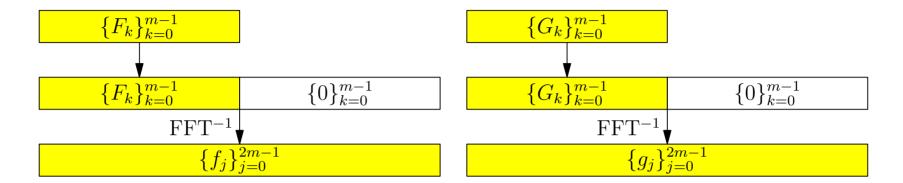
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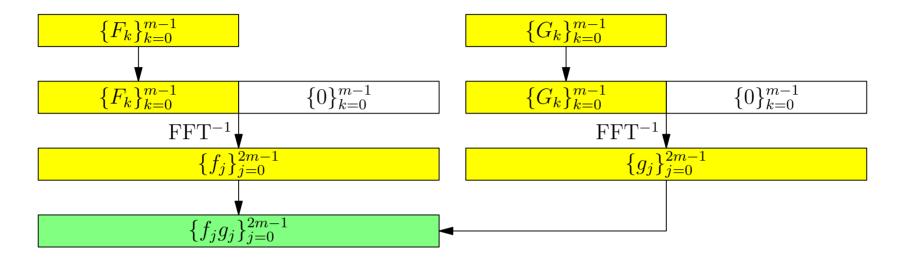
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- Explicit zero padding prevents mode m-1 from beating with itself and wrapping around to contaminate mode N=0 mod N.

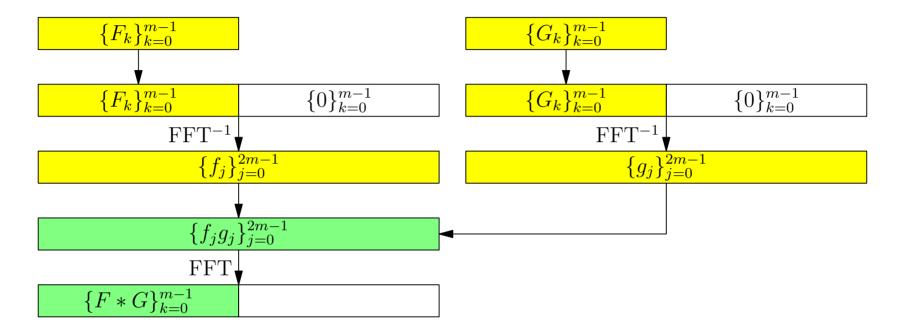
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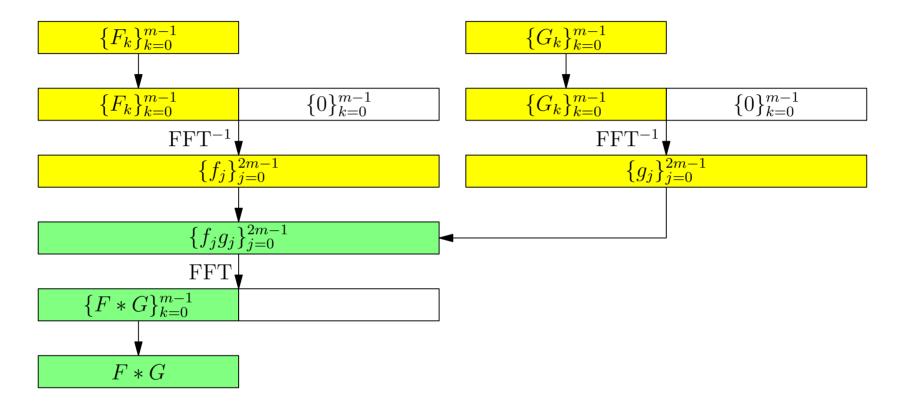
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$$f_{2\ell+1} = \sum_{k=0}^{m-1} \zeta_{2m}^{(2\ell+1)k} F_k = \sum_{k=0}^{m-1} \zeta_m^{\ell k} \zeta_{2m}^k F_k, \qquad \ell = 0, 1, \dots m-1.$$

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• This requires computing two subtransforms, each of size m, for an overall computational scaling of order $2m \log_2 m = N \log_2 m$.

$$2mF_k = \sum_{j=0}^{2m-1} \zeta_{2m}^{-kj} f_j$$

$$= \sum_{\ell=0}^{m-1} \zeta_{2m}^{-k2\ell} f_{2\ell} + \sum_{\ell=0}^{m-1} \zeta_{2m}^{-k(2\ell+1)} f_{2\ell+1}$$

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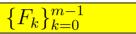
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- This in-place convolution was written to use six out-of-place transforms, thereby avoiding bit reversal at all levels.

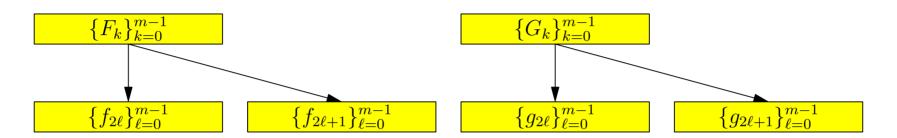
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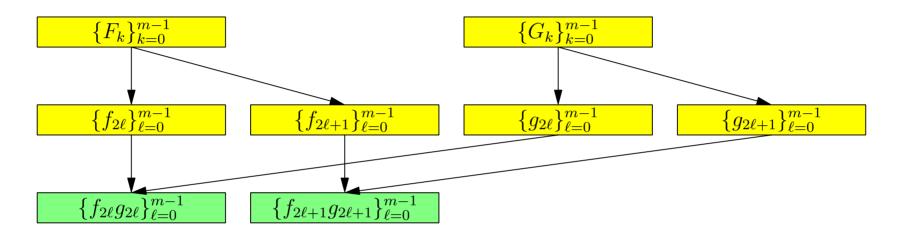


$$\{G_k\}_{k=0}^{m-1}$$

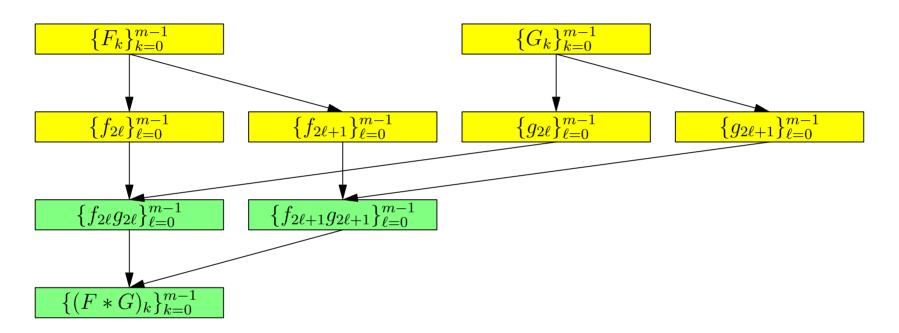
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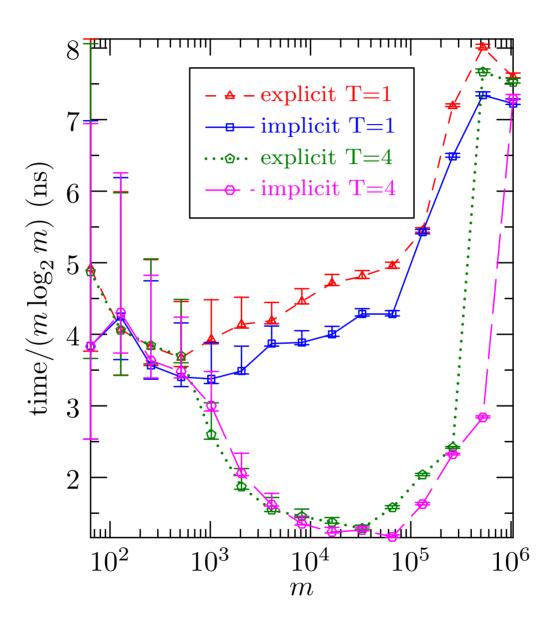


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```
Input: vector f, vector g
Output: vector f
u \leftarrow fft^{-1}(f);
v \leftarrow fft^{-1}(g);
u \leftarrow u * v;
for k = 0 to m - 1 do
  f[k] \leftarrow \zeta_{2m}^k f[k];
 | \mathbf{g}[k] \leftarrow \zeta_{2m}^k \mathbf{g}[k];
end
v \leftarrow fft^{-1}(f);
f \leftarrow fft^{-1}(g);
v \leftarrow v * f;
f \leftarrow fft(u);
u \leftarrow fft(v);
for k = 0 to m - 1 do
 |\mathsf{f}[k] \leftarrow \mathsf{f}[k] + \zeta_{2m}^{-k} \mathsf{u}[k];
end
return f/(2m);
```

Implicit Padding in 1D

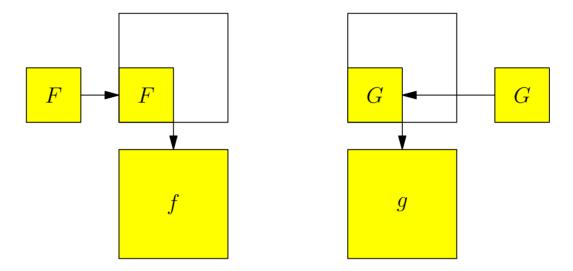


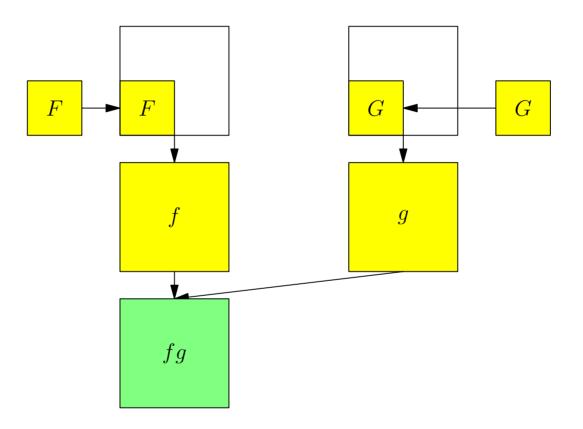
• An explicitly padded convolution in 2 dimensions requires 12 padded FFTs, and 4 times the memory of a cyclic convolution.

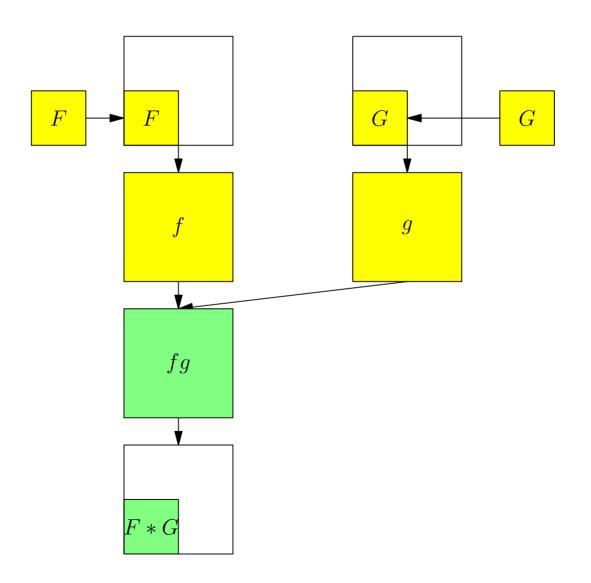
F

G



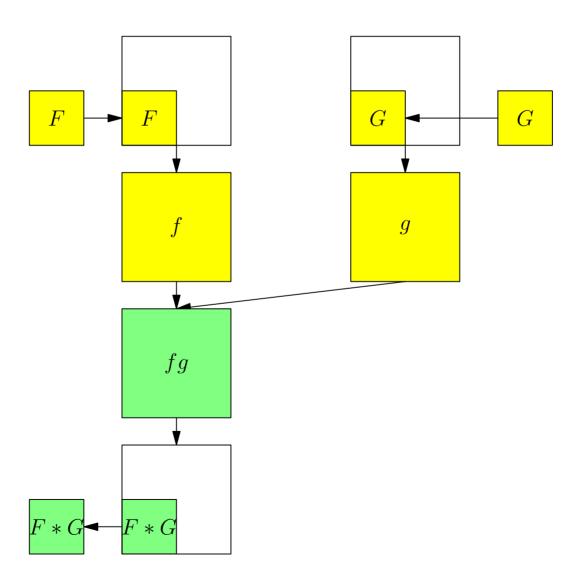






Convolutions in Higher Dimensions

• An explicitly padded convolution in 2 dimensions requires 12 padded FFTs, and 4 times the memory of a cyclic convolution.



Recursive Convolution

• Naive way to compute a multiple-dimensional convolution:



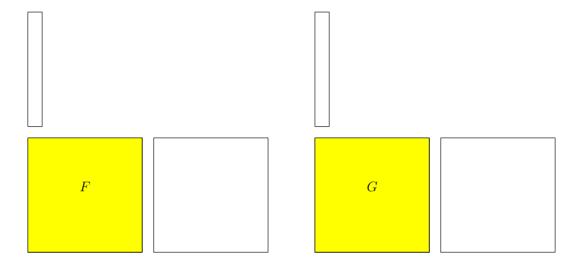
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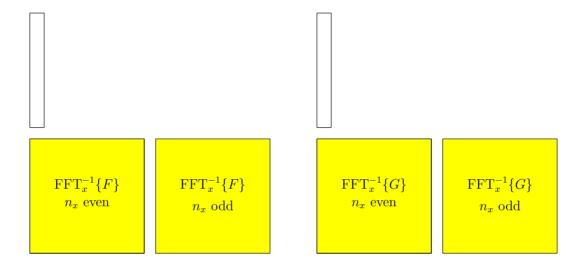
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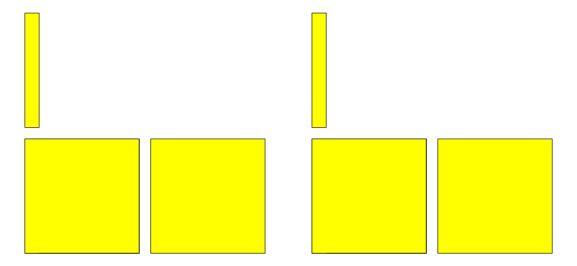


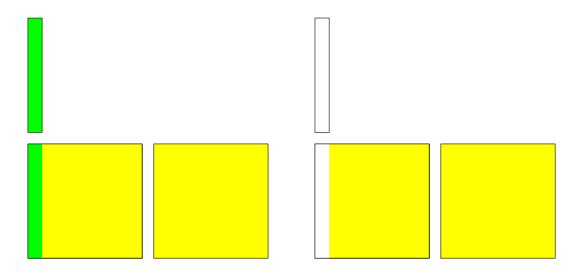
• The technique of *recursive convolution* allows one to avoid computing and storing the entire Fourier image of the data:

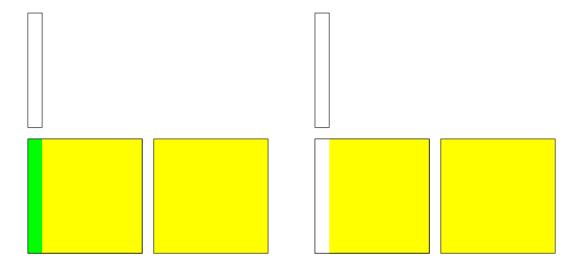


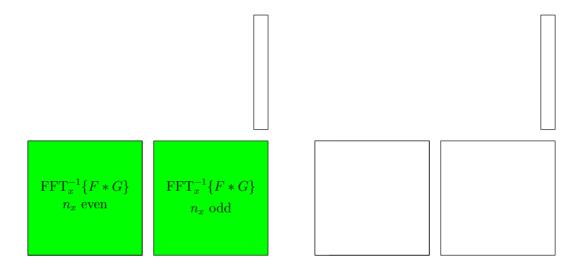


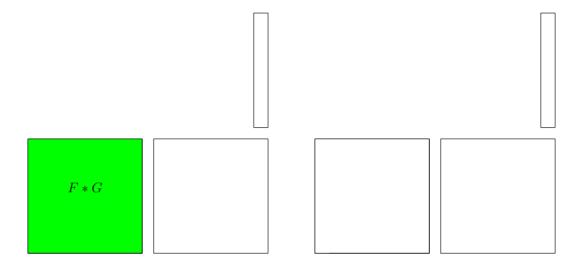


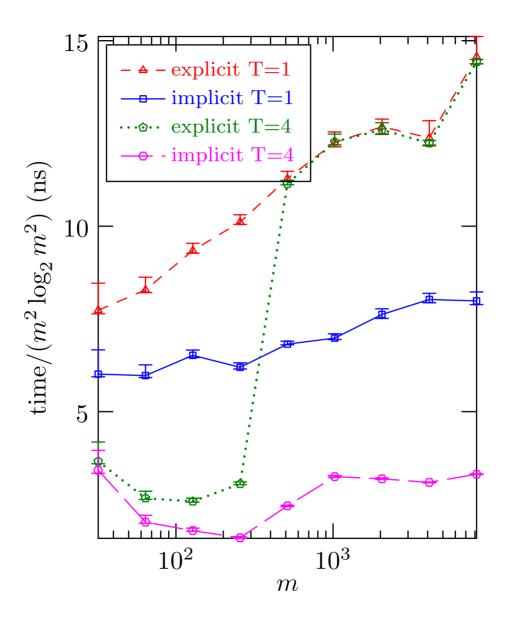


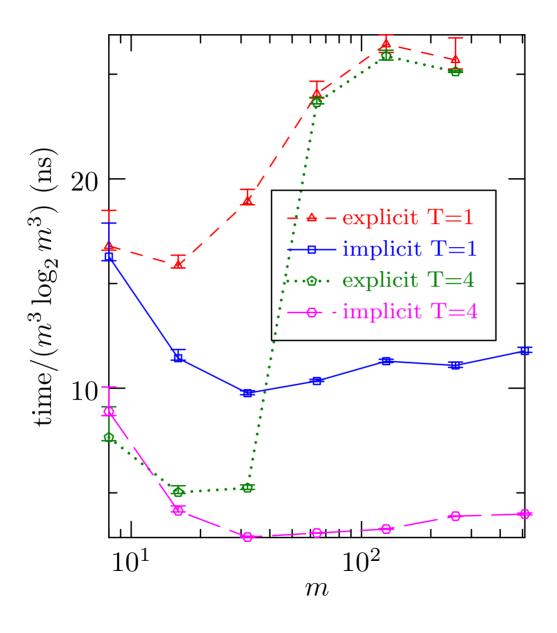












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- The ratio (2m-1)/(3m-2) of the number of physical to total modes is asymptotic to 2/3 for large m.
- A *Hermitian convolution* arises since the input vectors are real:

$$f_{-k} = \overline{f_k}.$$

Hermitian Convolution

• The backwards implicitly padded centered Hermitian transform appears as

$$u_{3\ell+r} = \sum_{k=0}^{m-1} \zeta_m^{\ell k} w_{k,r},$$

where

$$w_{k,r} \doteq \begin{cases} U_0 + \text{Re}\,\zeta_3^{-r} U_{-m} & \text{if } k = 0, \\ \zeta_{3m}^{rk} \left(U_k + \zeta_3^{-r} \overline{U_{m-k}} \right) & \text{if } 1 \le k \le m-1. \end{cases}$$

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• We exploit the Hermitian symmetry $w_{k,r} = \overline{w_{m-k,r}}$ to reduce the problem to three complex-to-real Fourier transforms of the first c+1 components of $w_{k,r}$ (one for each r=-1,0,1), where $c \doteq |m/2|$ zeros.

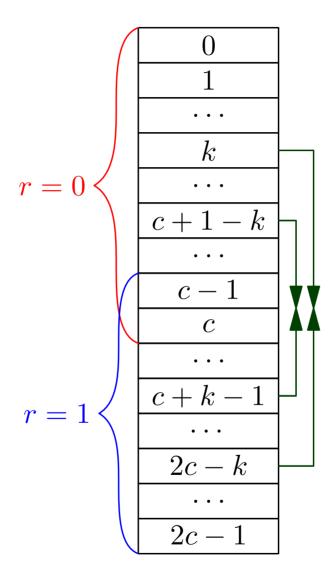
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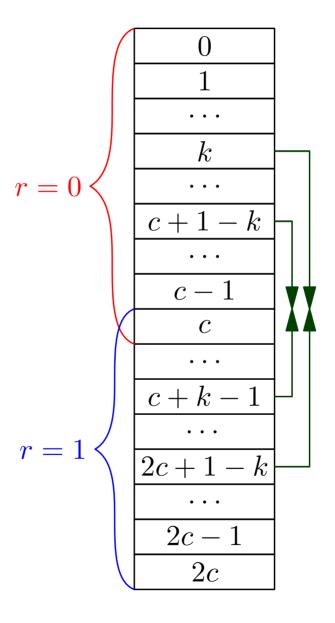
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- Unrolling the loop to process four inputs and outputs simultaneously allows loop independence to be achieved, significantly improving performance in both the serial and parallel contexts.
- As a result, even in 1D, implicit dealiasing of pseudospectral convolutions is now significantly faster than explicit zero padding [Roberts & Bowman 2016].

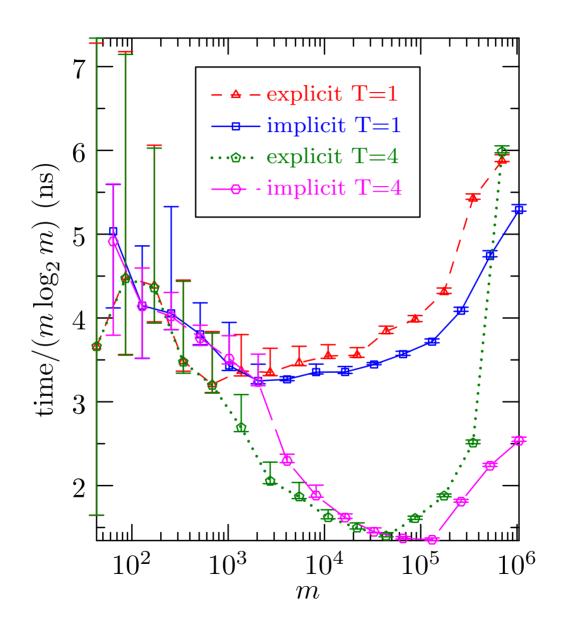
Hermitian Convolution for m = 2c



Hermitian Convolution for m = 2c + 1



1D Implicit Hermitian Convolution



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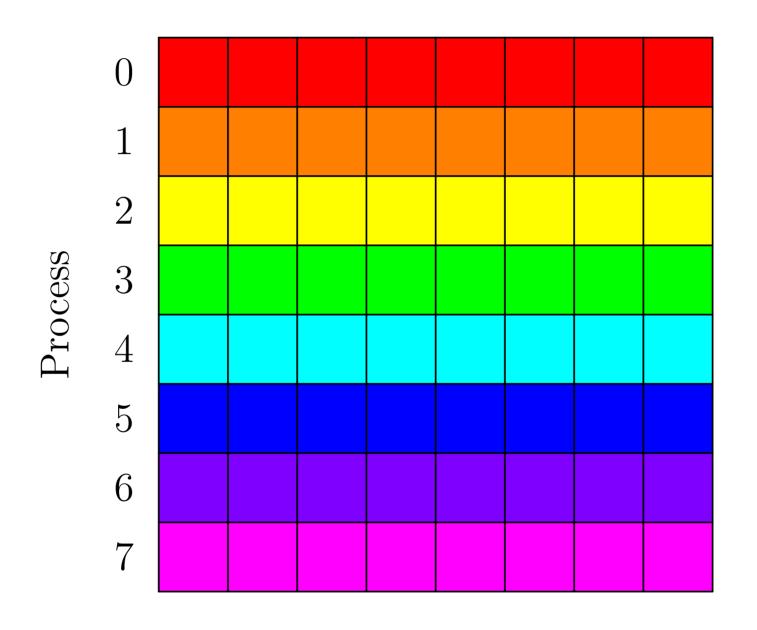
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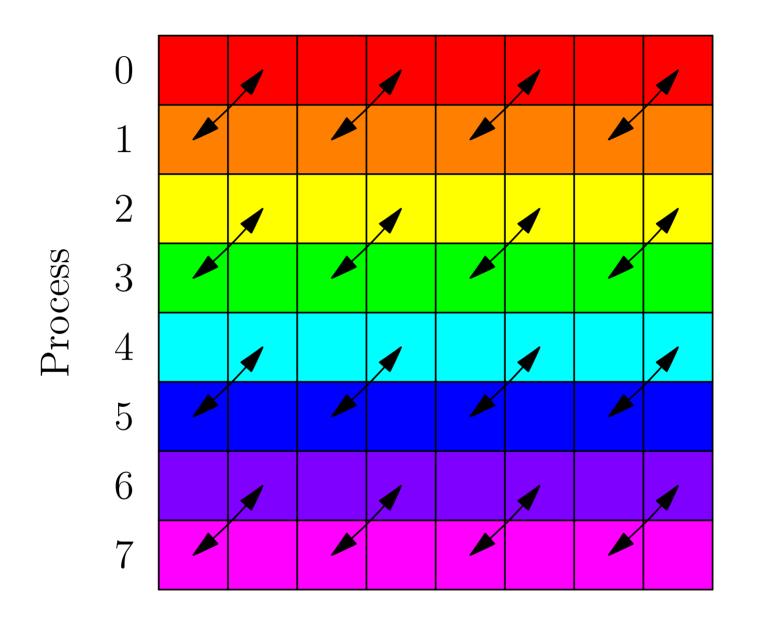
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- We have developed an adaptive algorithm, dynamically tuned to choose the optimal block size.

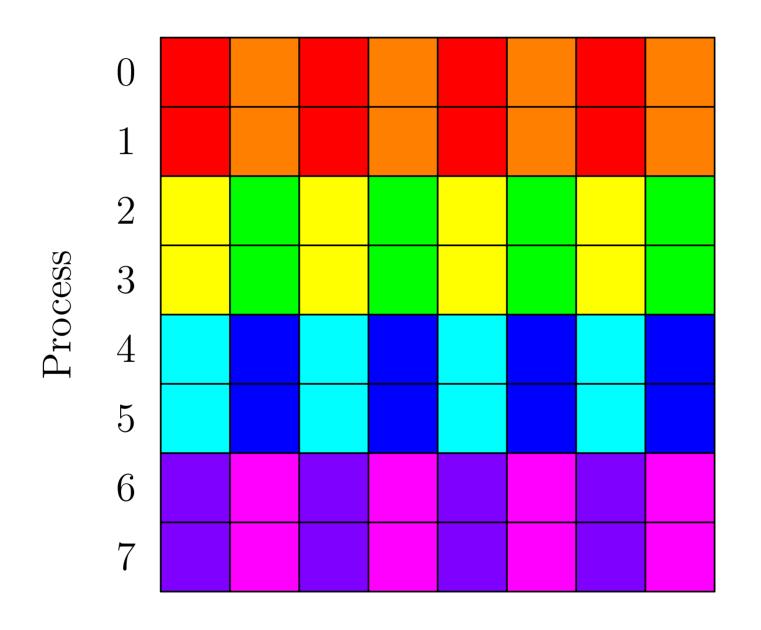
 8×8 Block Transpose over 8 processors



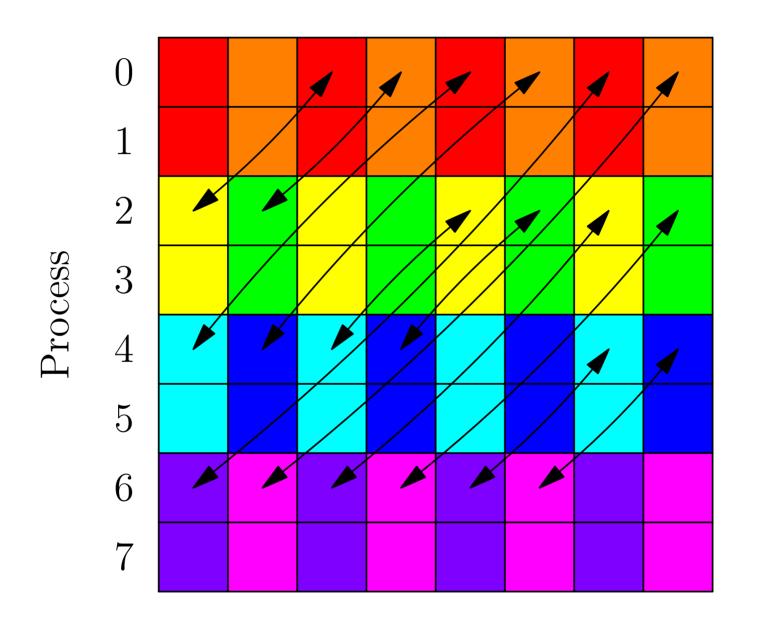
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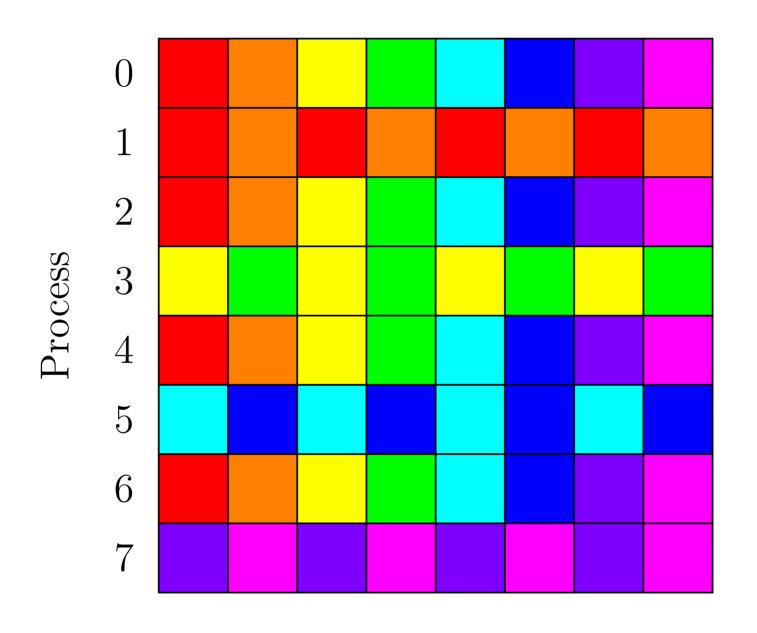
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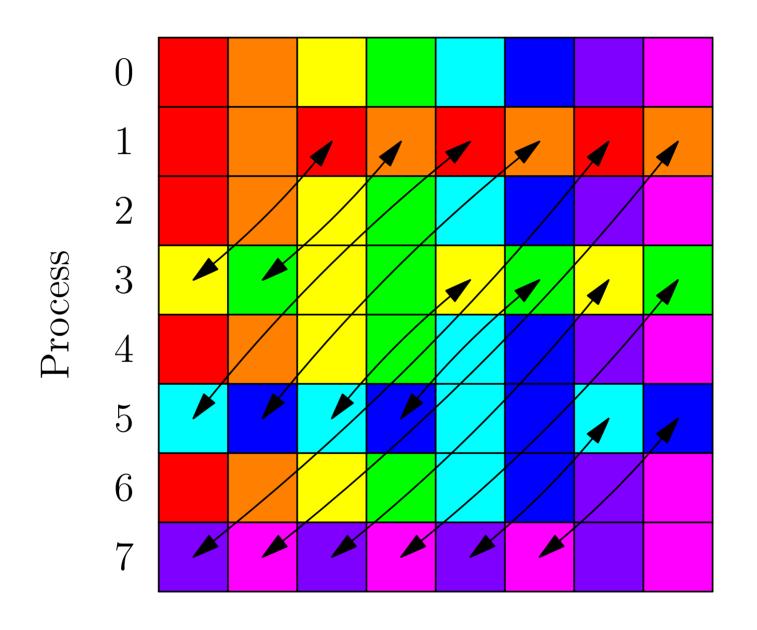
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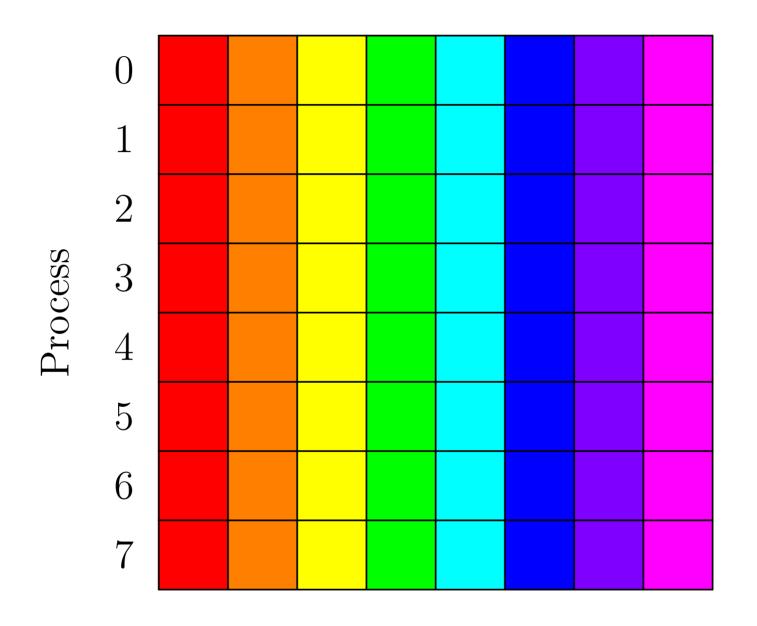
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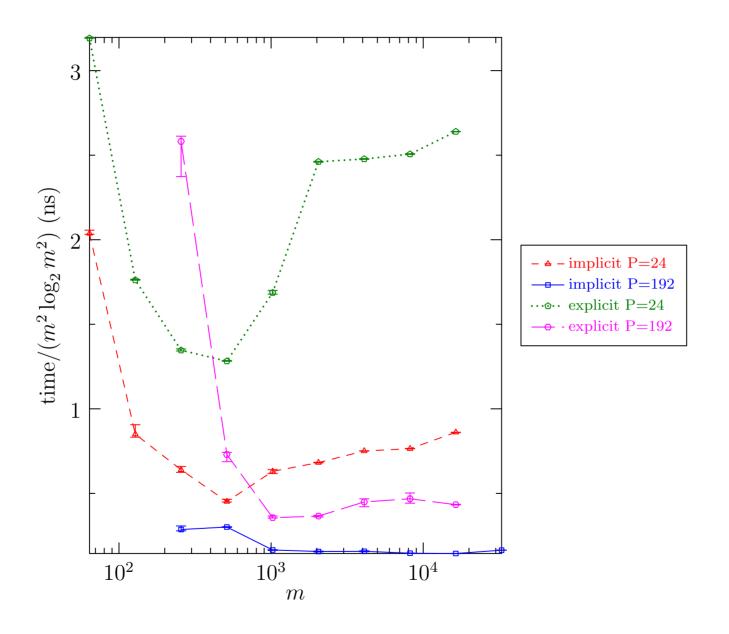
Advantages of Hybrid MPI/OpenMP

- Use hybrid OpenMPI/MPI with the optimal number of threads:
 - yields larger communication block size;
 - local transposition is not required within a single MPI node;
 - allows smaller problems to be distributed over a large number of processors;
 - for 3D FFTs, allows for more slab-like than pencil-like models, reducing the size of or even eliminating the need for a second transpose;
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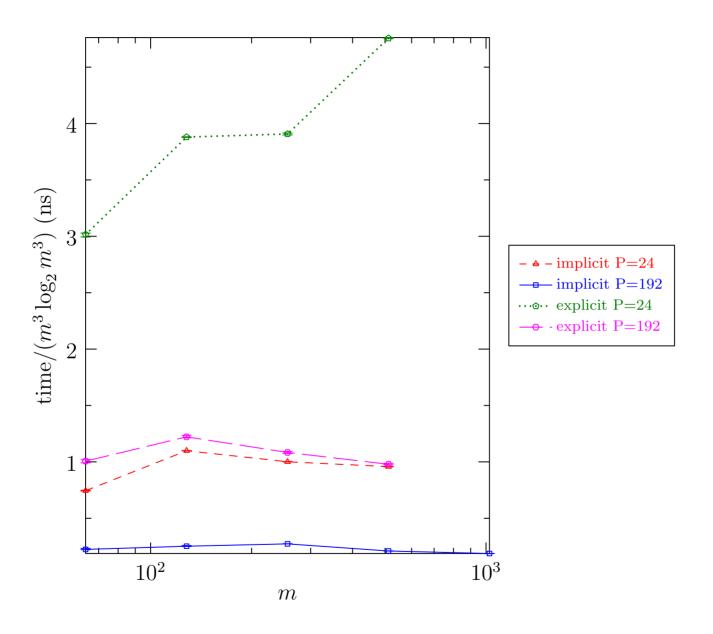
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 - sometimes more efficient (by a factor of 2) than pure MPI.
- The use of nonblocking MPI communications allows us to overlap computation with communication: this can yield up to an additional 32% performance gain for implicitly dealiased convolutions, for which a natural parallelism exists between communication and computation.

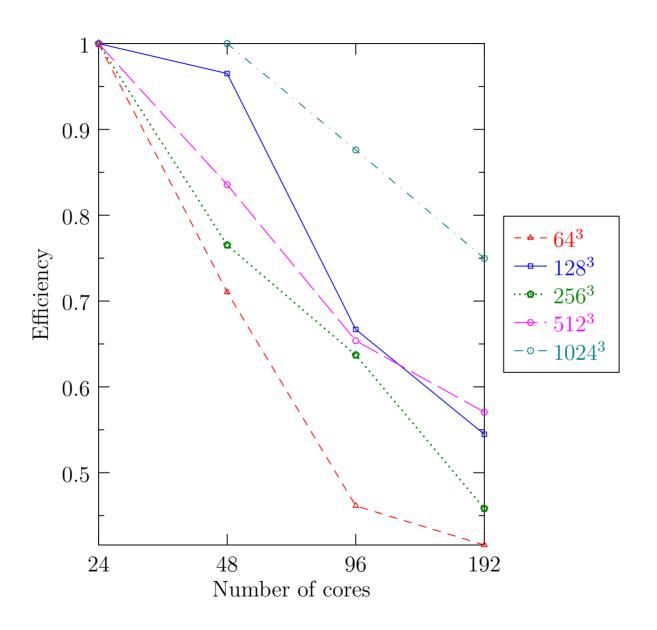
Pure MPI 2D Convolutions



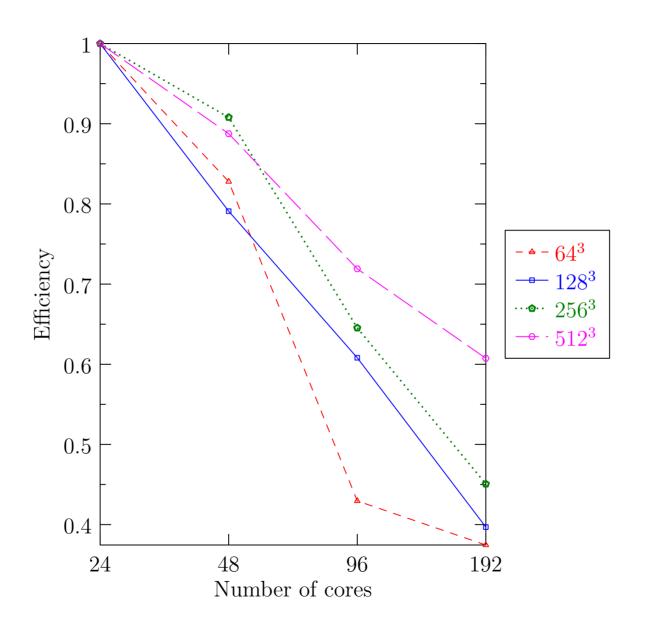
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MPI 3D Implicit Parallel Efficiency



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- Direct transposition involves P-1 communications per process, each of size N^2/P^2 , for a total per-process data transfer of

$$\frac{P-1}{P^2}N^2.$$

Block Transpose

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- Outer: Over each team of a processes, transpose the $a \times a$ matrix of $N/a \times M/a$ blocks.

Communication Costs

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whereas a block transpose requires

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• Let $L = \tau_{\ell}/\tau_d$ be the effective communication block length.

Direct vs. Block Transposes

Since

$$T_D - T_B = \tau_d \left(P + 1 - a - \frac{P}{a} \right) \left(L - \frac{NM}{P^2} \right),$$

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• For $NM < P^2L$, we see that T_B is convex, with a minimum at $a = \sqrt{P}$.

Optimal Number of Threads

• The minimum value of T_B is

$$T_B(\sqrt{P}) = 2\tau_d \left(\sqrt{P} - 1\right) \left(L + \frac{NM}{P^{3/2}}\right)$$
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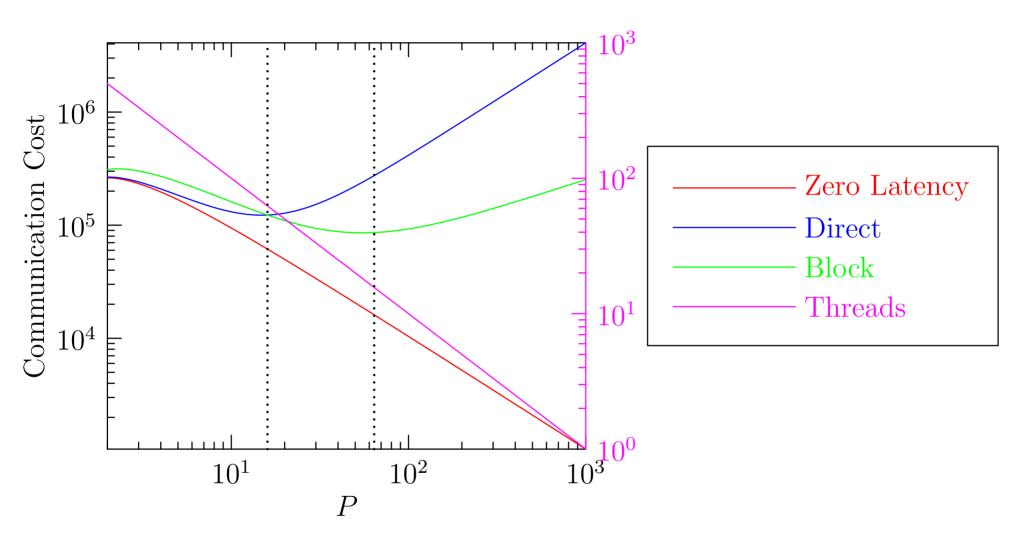
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• If the matrix dimensions satisfy NM > L, as is typically the case, this minimum occurs above the transition value $(NM/L)^{1/2}$.

Transpose Communication Costs



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- Hybrid MPI/OpenMP is often more efficient than pure MPI for distributed matrix transposes.
- The hybrid paradigm provides an optimal setting for nonlocal computationally intensive operations found in applications like the fast Fourier transform.
- The advent of implicit dealiasing of convolutions makes overlapping transposition with FFT computation feasible.

• Writing of a high-performance dealiased pseudospectral code is now a relatively straightforward exercise. For example, see the protodns project at

http://github.com/dealias/dns

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